

Just Trial Once: Ongoing Causal Validation of Machine Learning Models

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Overview

1. Introduce the problem and its key challenges.
2. Introduce a formal setup for approaching the problem.
3. State assumptions that address the key challenges.
4. Bound the causal effect of interest.

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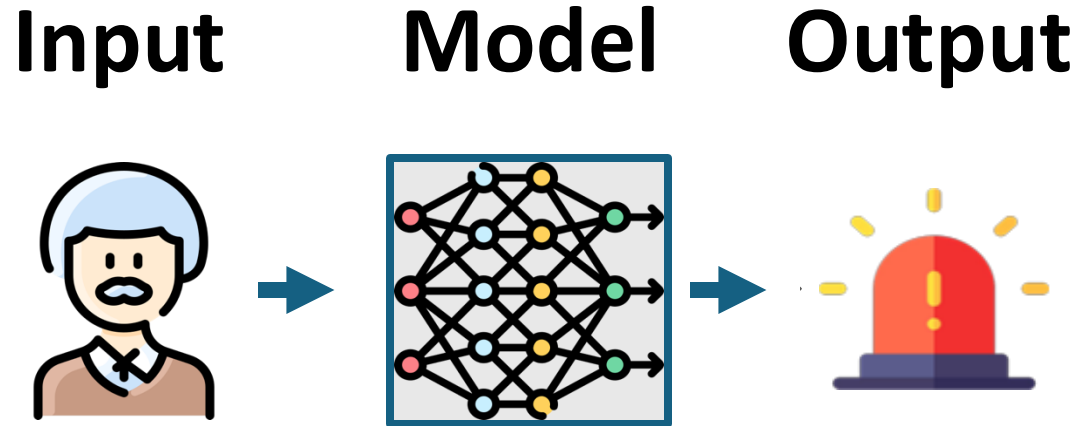
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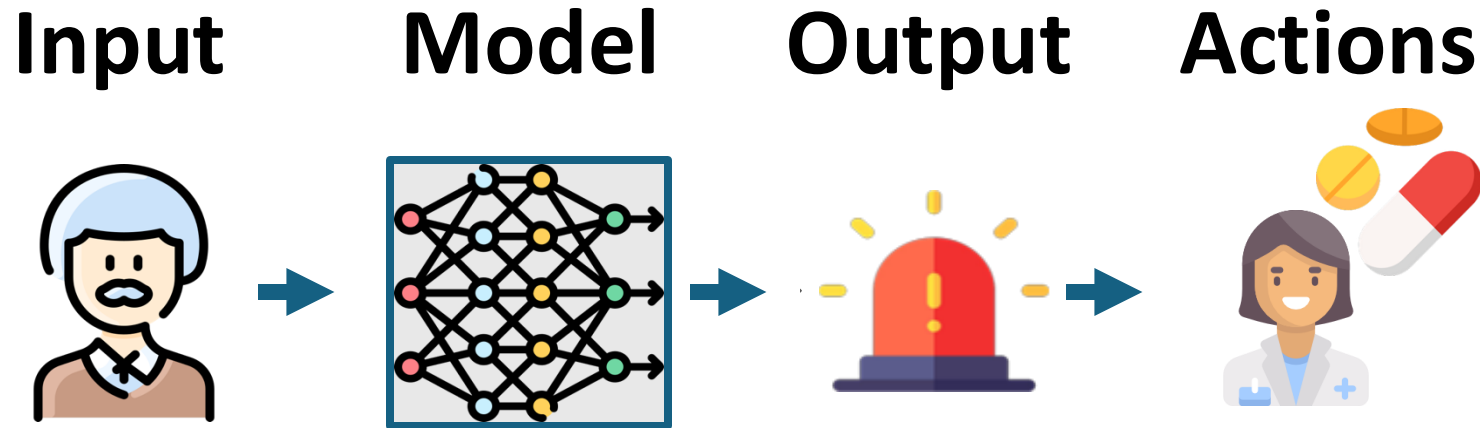
What is causal validation of an ML model?

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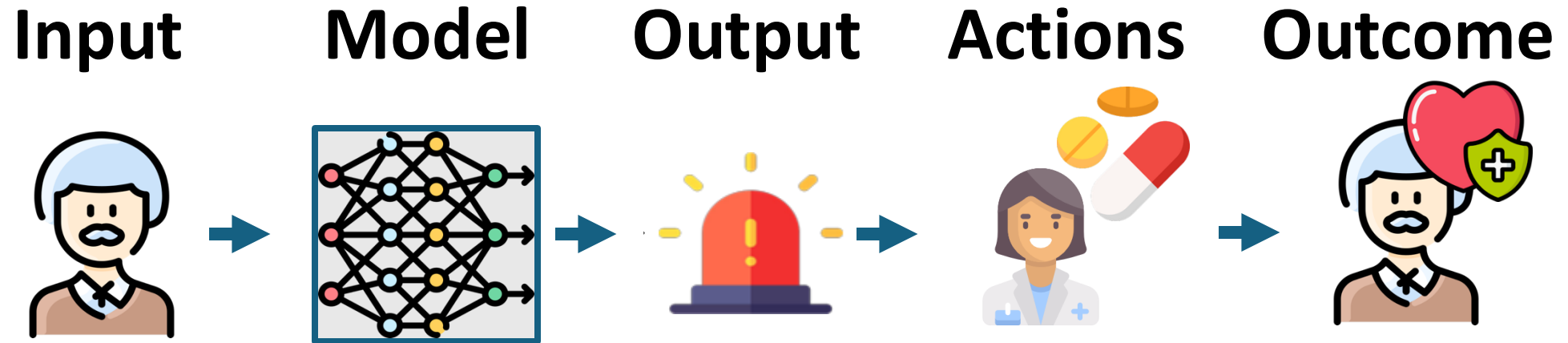
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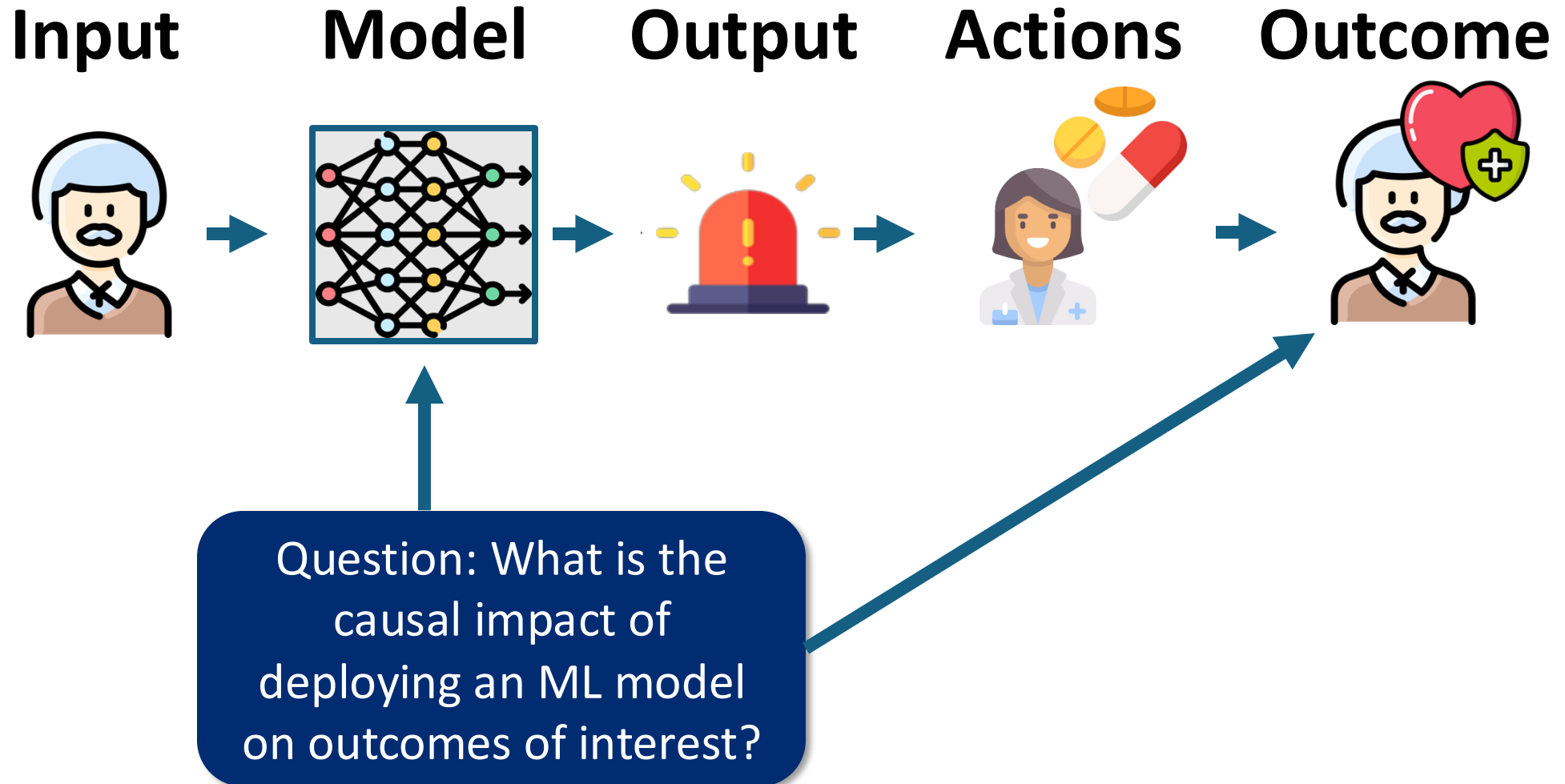
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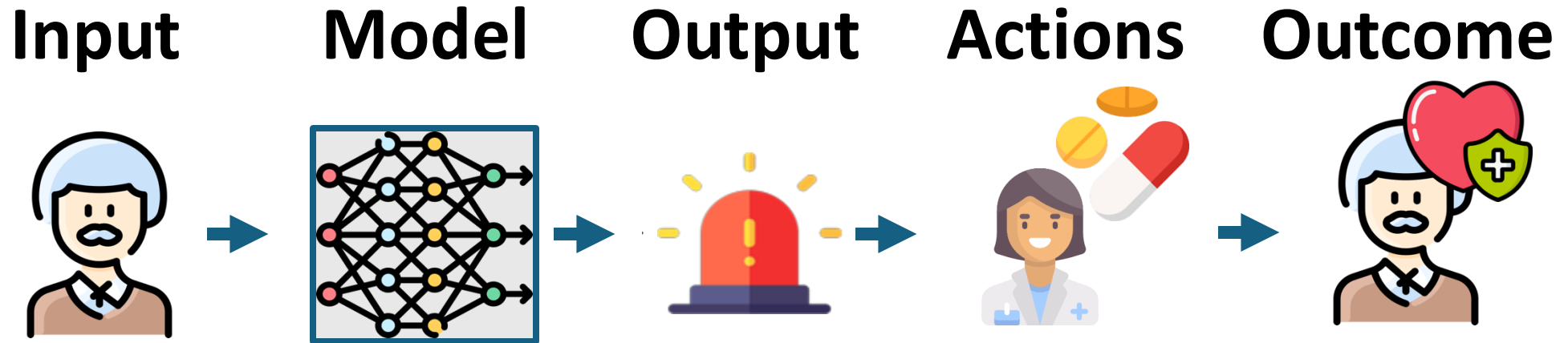


1. ML model produces an output based on patient information.
2. A decision-maker sees the model output and takes an action.
3. We observe outcomes, such as survival.

What is causal validation of an ML model?



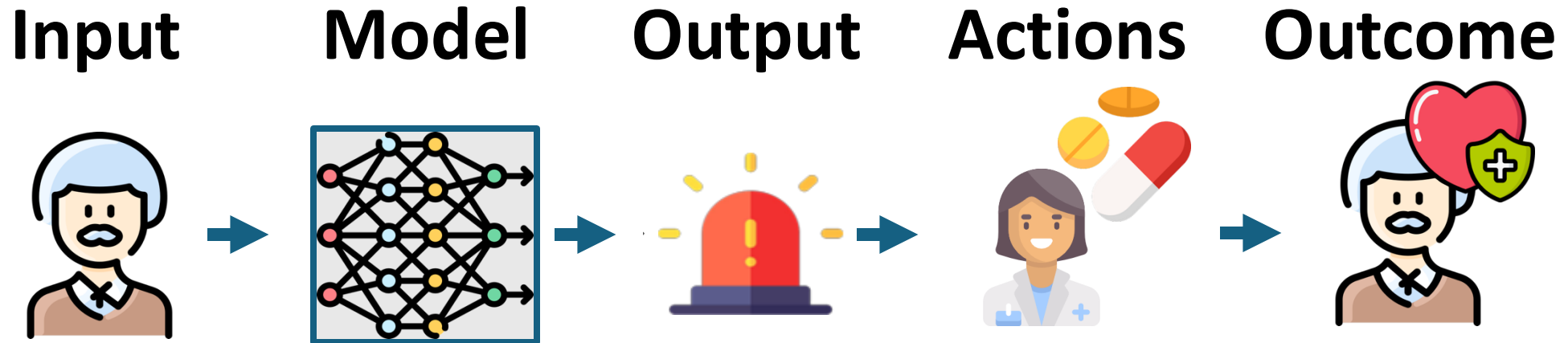
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This is a general problem:

- Does deploying ML models in hospitals improve patient survival?

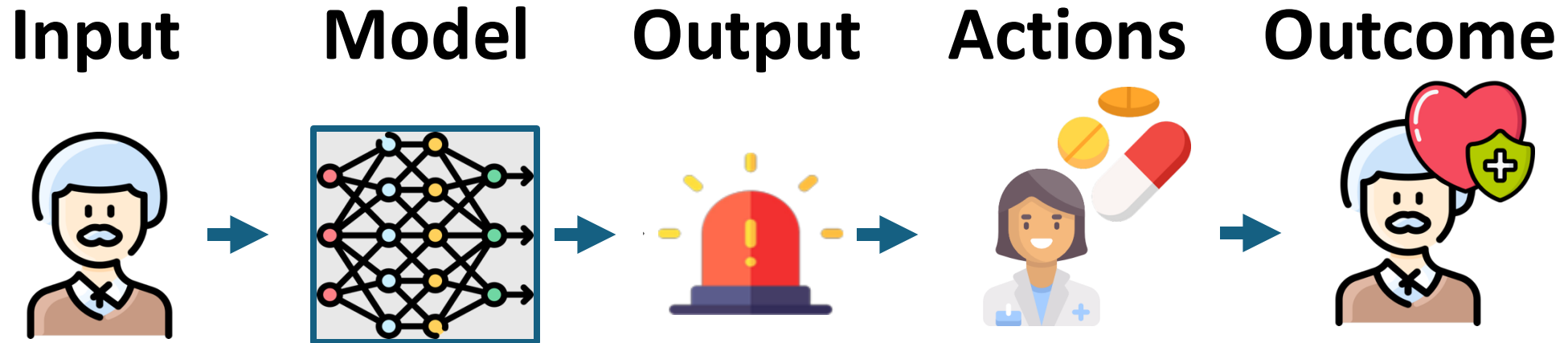
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- Does deploying ML models in hospitals improve patient survival?
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- Does using bail recommendation systems improve defendant return rates to the courtroom?

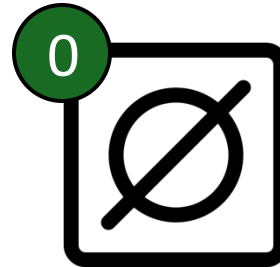
Cluster Randomized Controlled Trials (RCTs)

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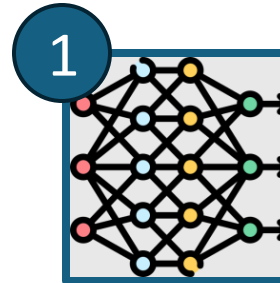
Cluster

Assignment

Outcomes

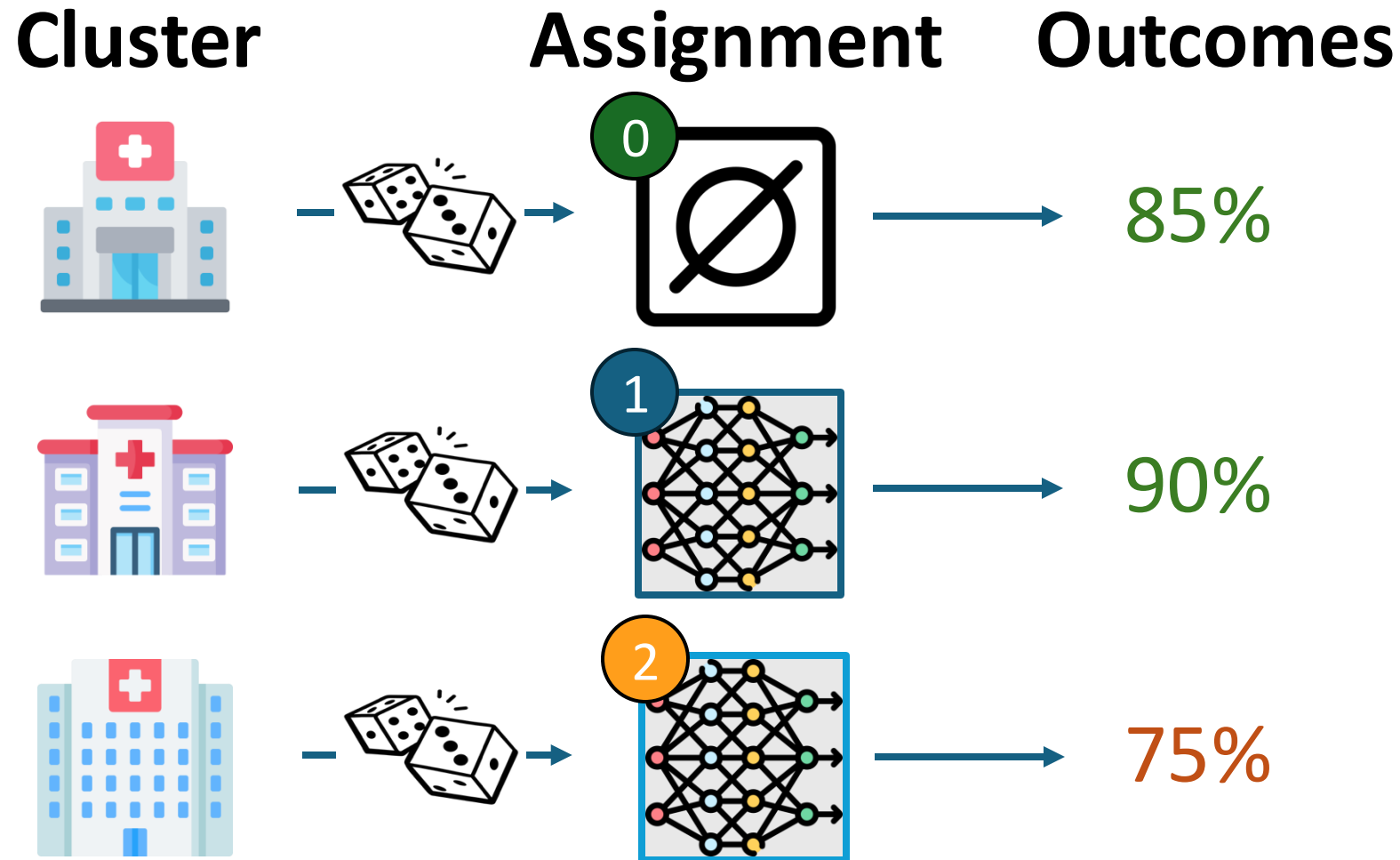


85%

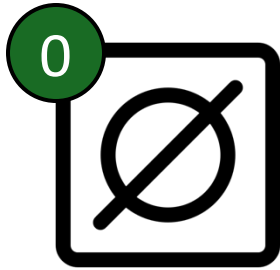


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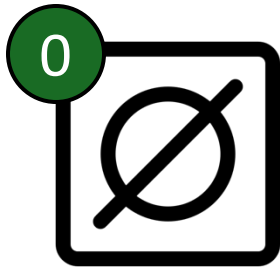
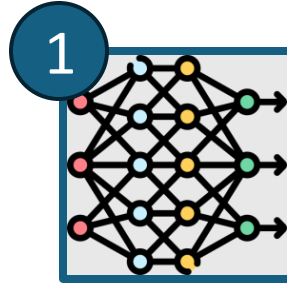
Cluster RCT Design with Multiple Models



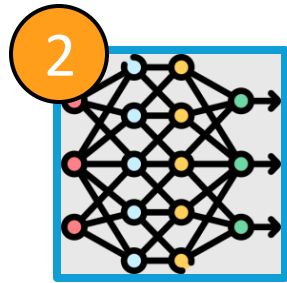
Limitations of Cluster RCTs



vs.

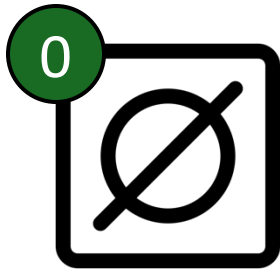


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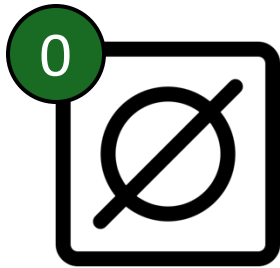
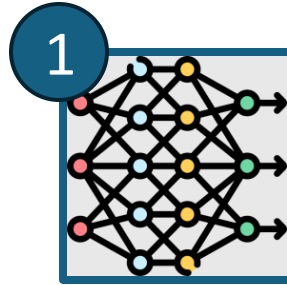


Allows for evaluation of models
trialed in the cluster RCT.

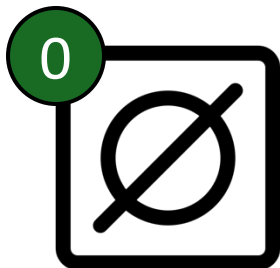
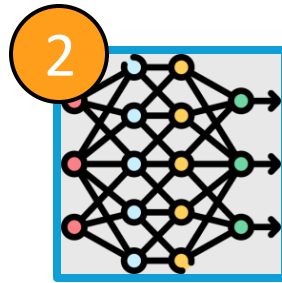
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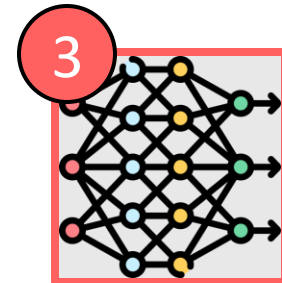
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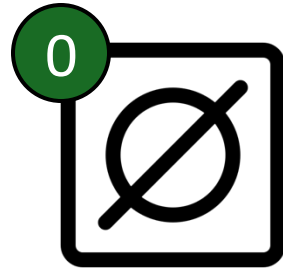
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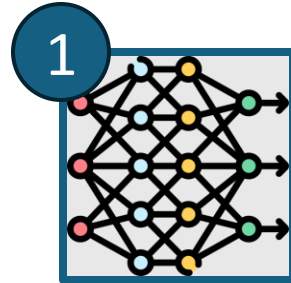
Does not allow for evaluation of a new, never-trialed models.

Our Goal: Just Trial Once

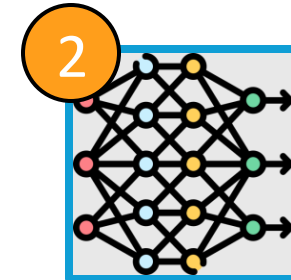
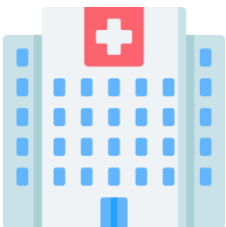
Cluster Assignment Outcomes



85%



90%



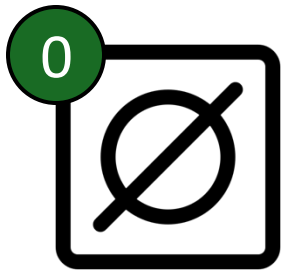
75%

Given data from a
cluster RCT...

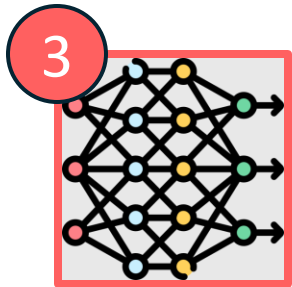
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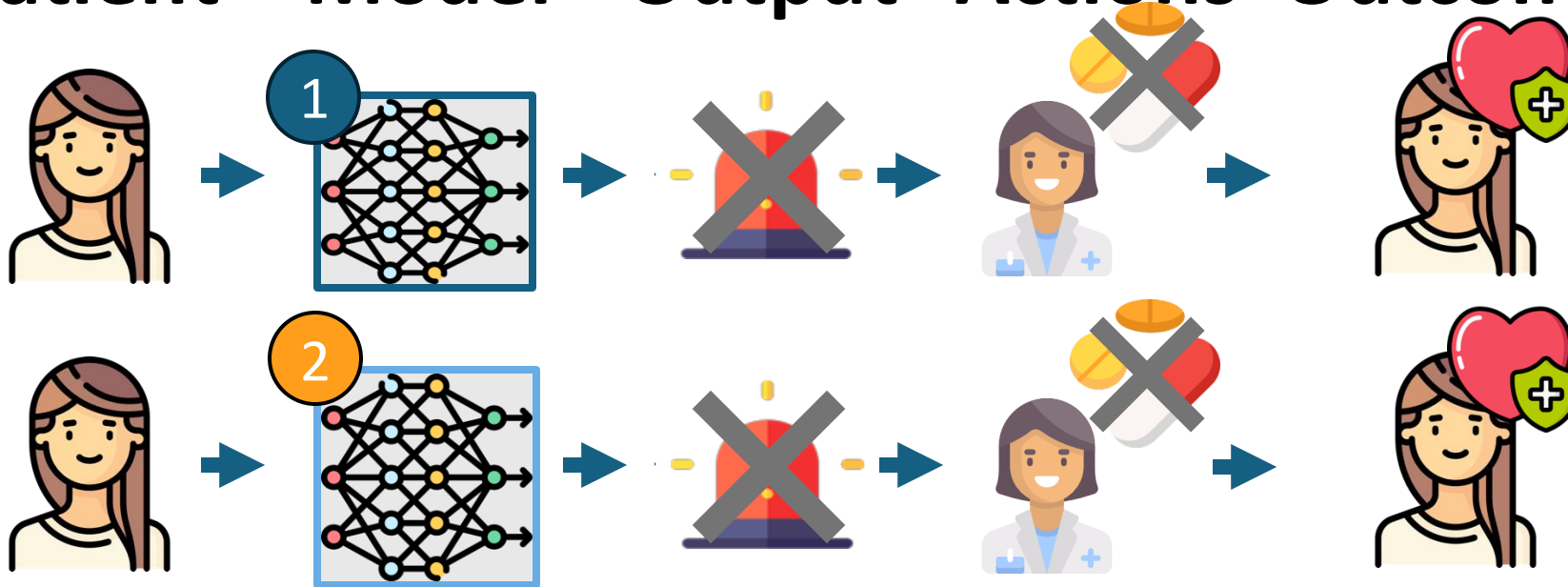
87% - 92%

... bound the outcome of interest
under a never-deployed model
between L and U .

Two Challenges: **Coverage** and Trust

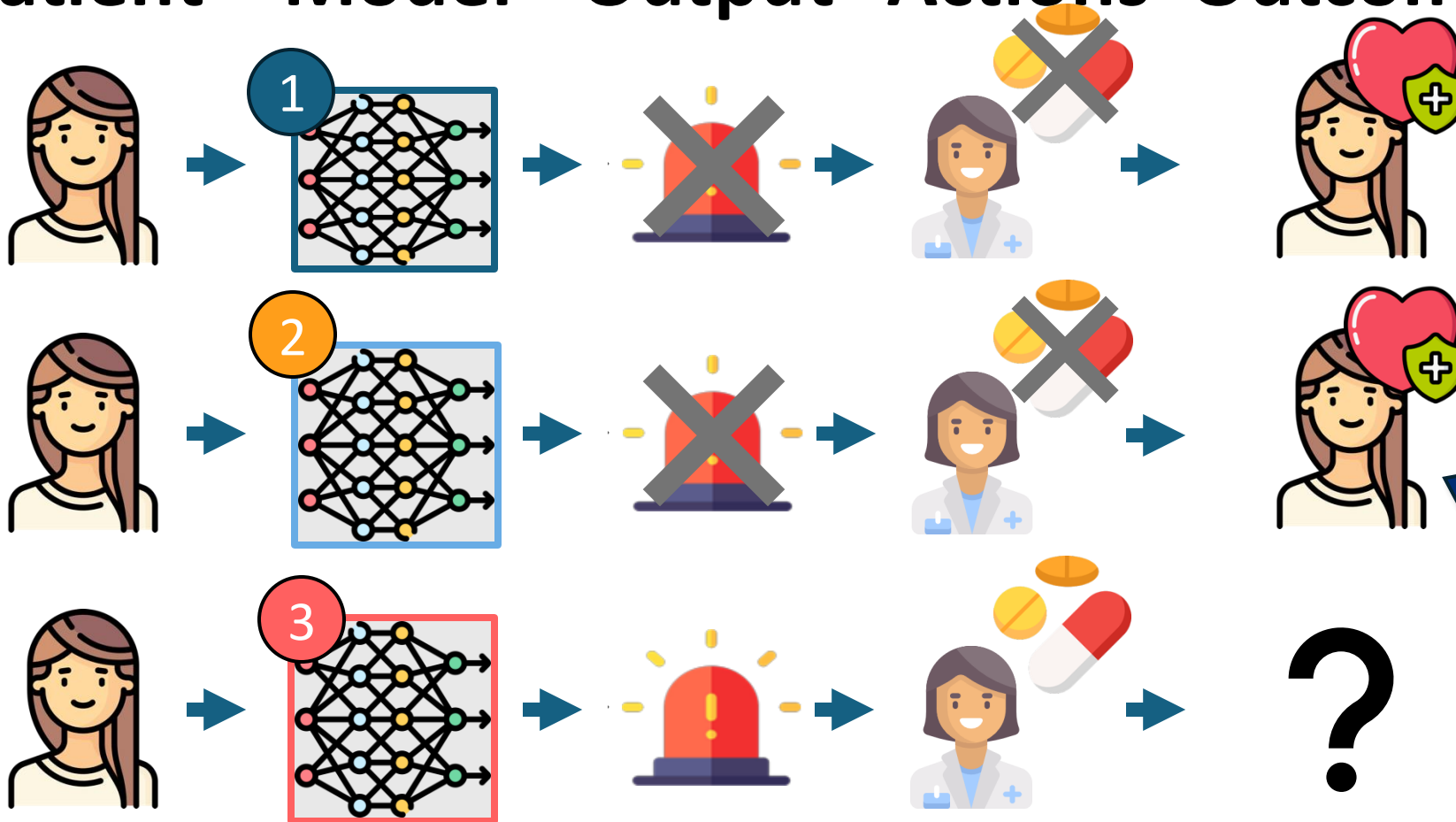
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Patient Model Output Actions Outcome



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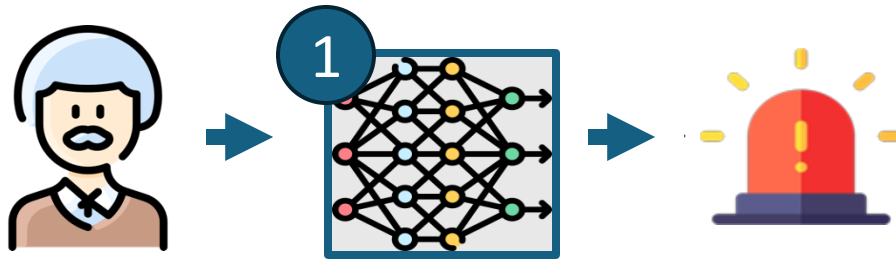
Patient Model Output Actions Outcome



We have no RCT data on what happens when alerting on individuals like this.

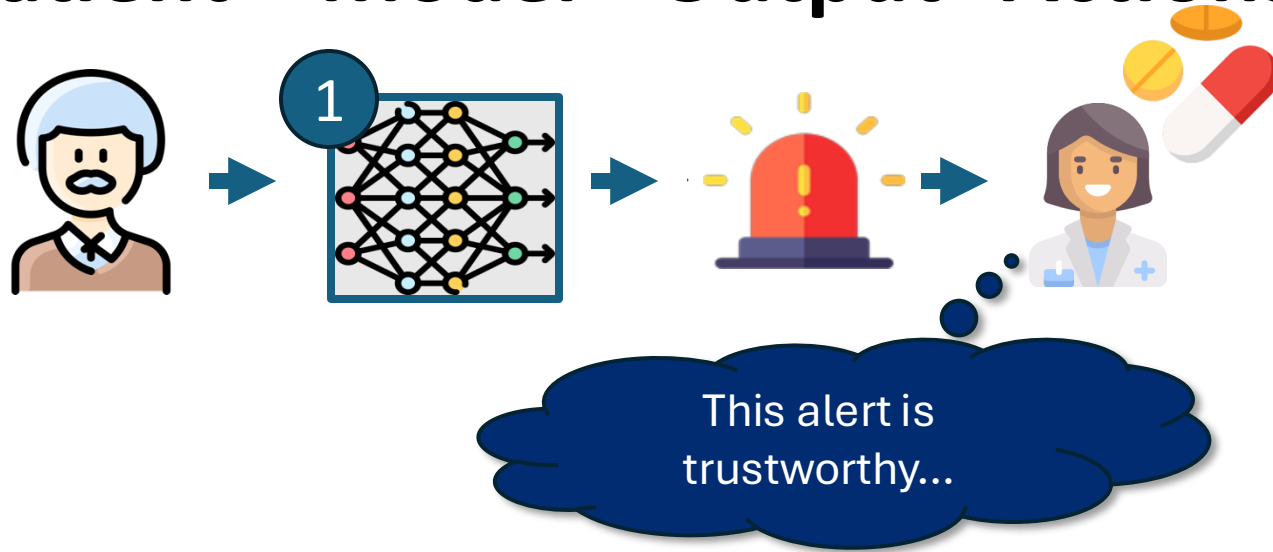
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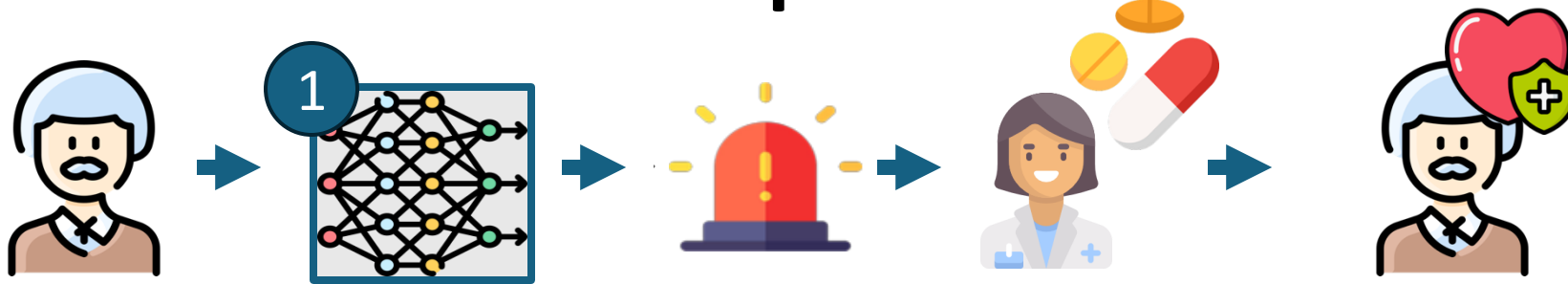
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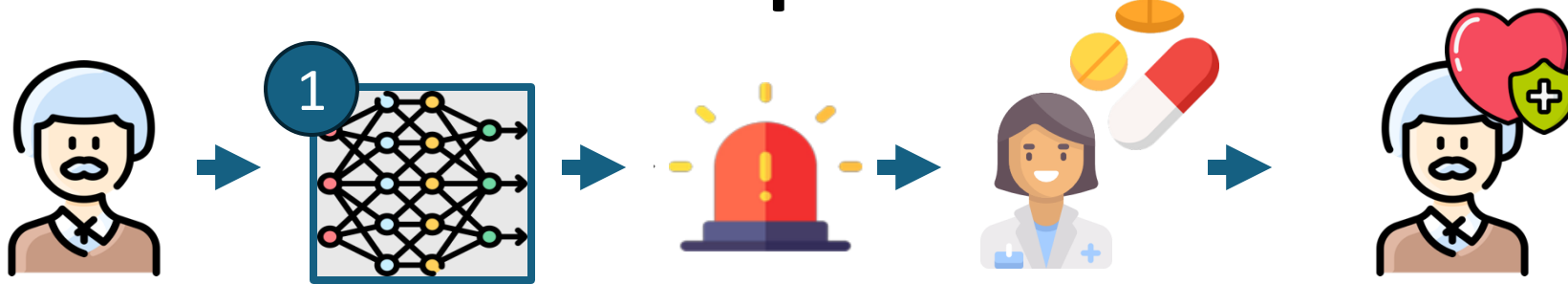
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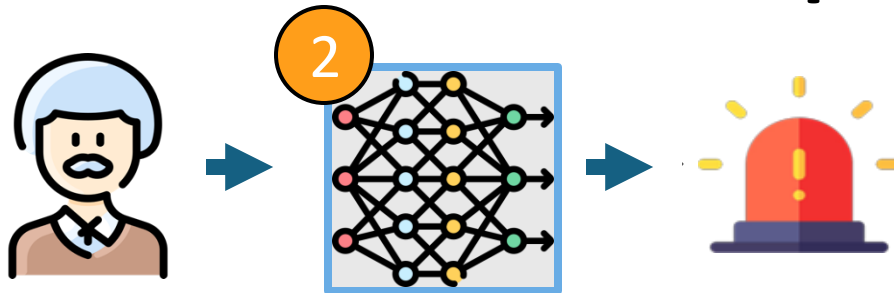


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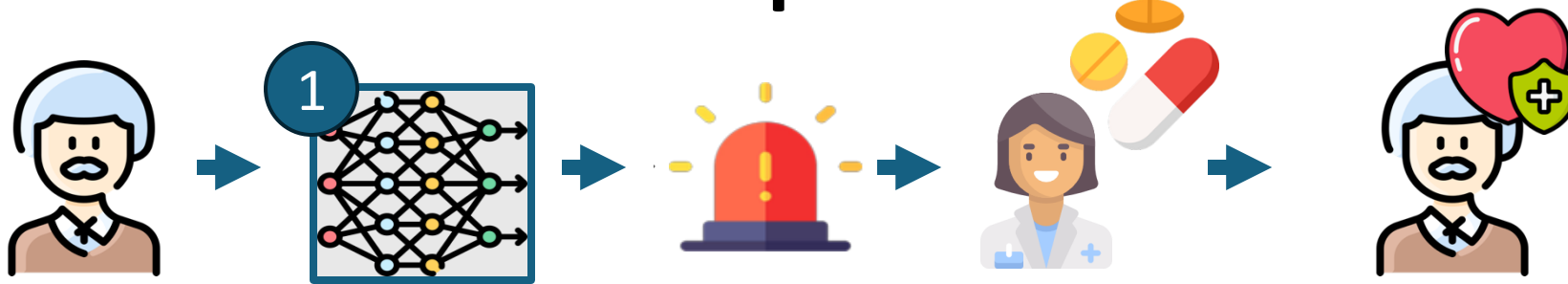


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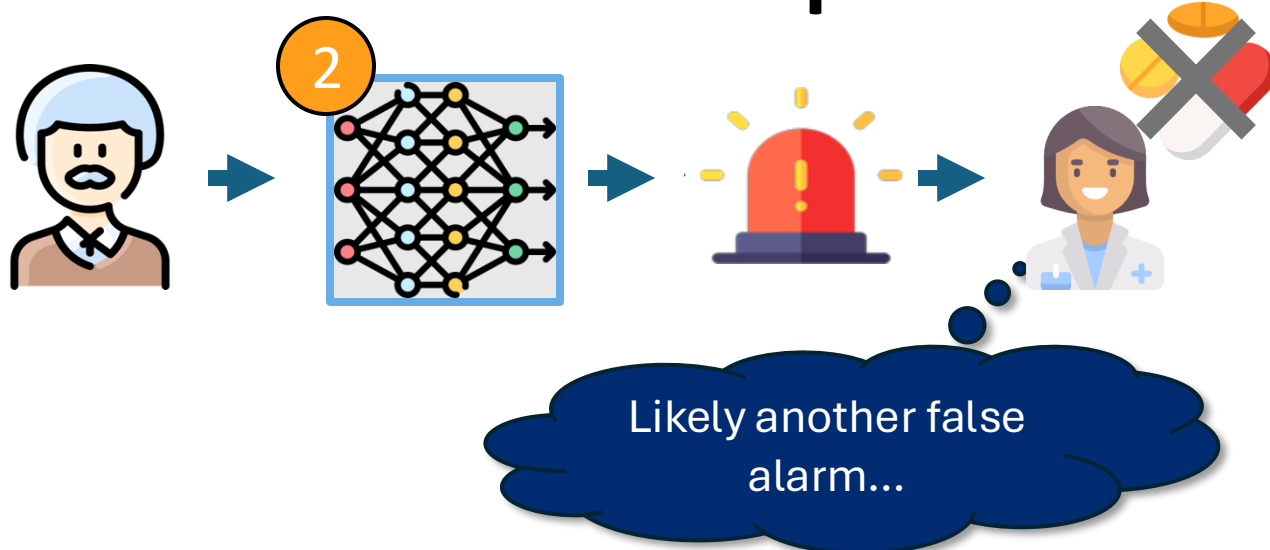


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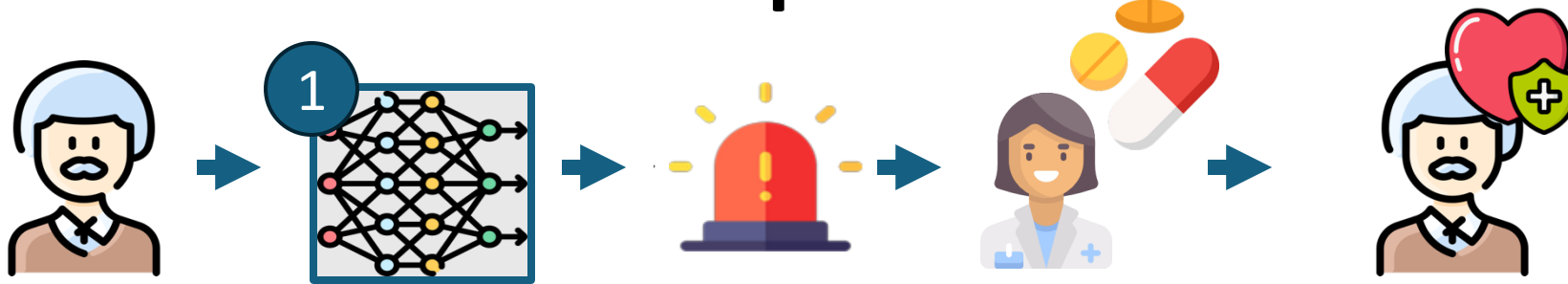


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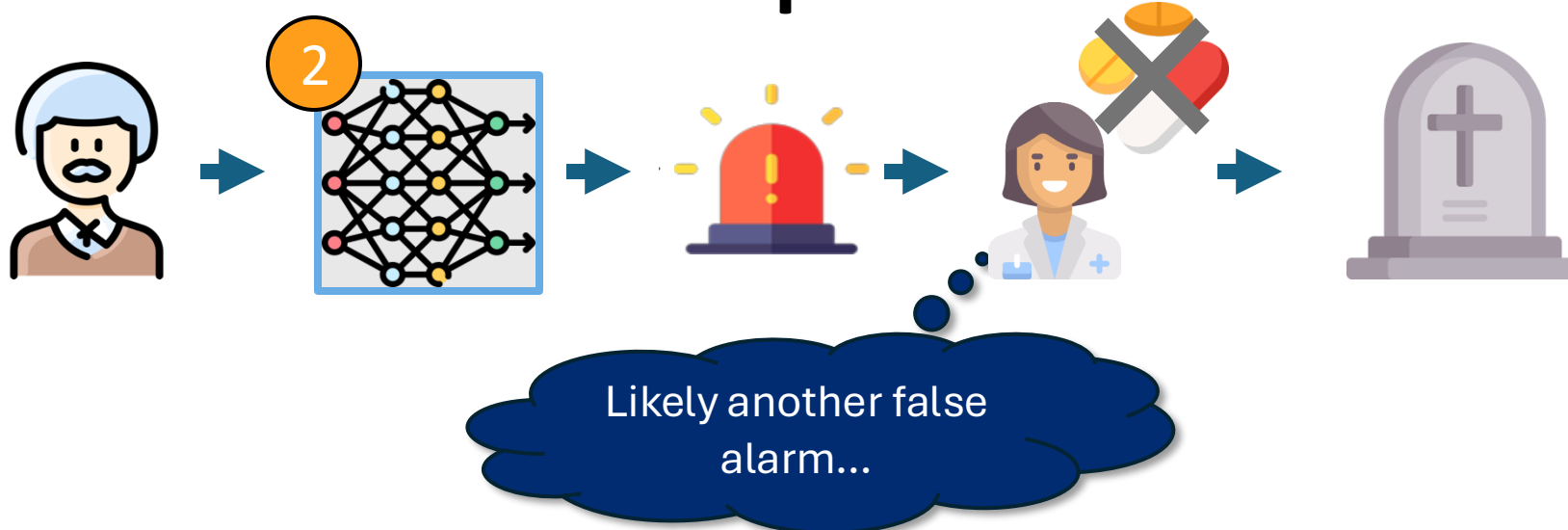


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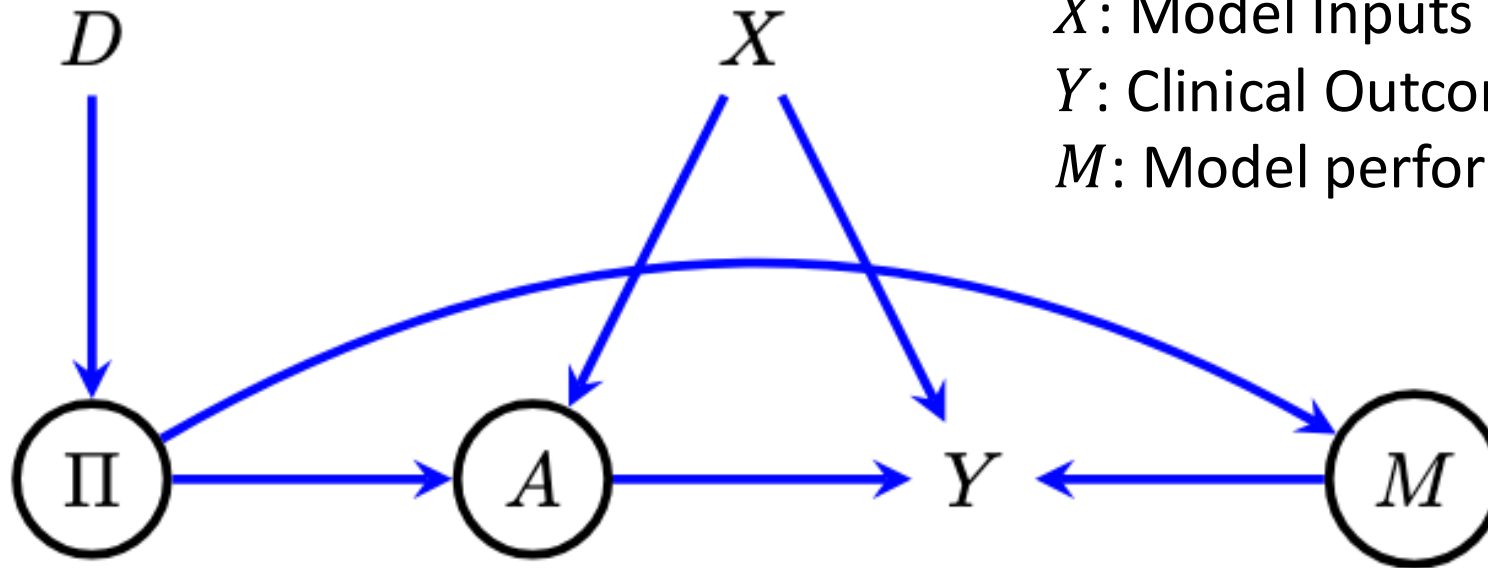


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Problem Setup

D : Indicator of trial arm
 Π : Deployed model/policy
 A : Model Output
 X : Model Inputs
 Y : Clinical Outcome
 M : Model performance metric



Assumed causal data-generating process

Problem Setup

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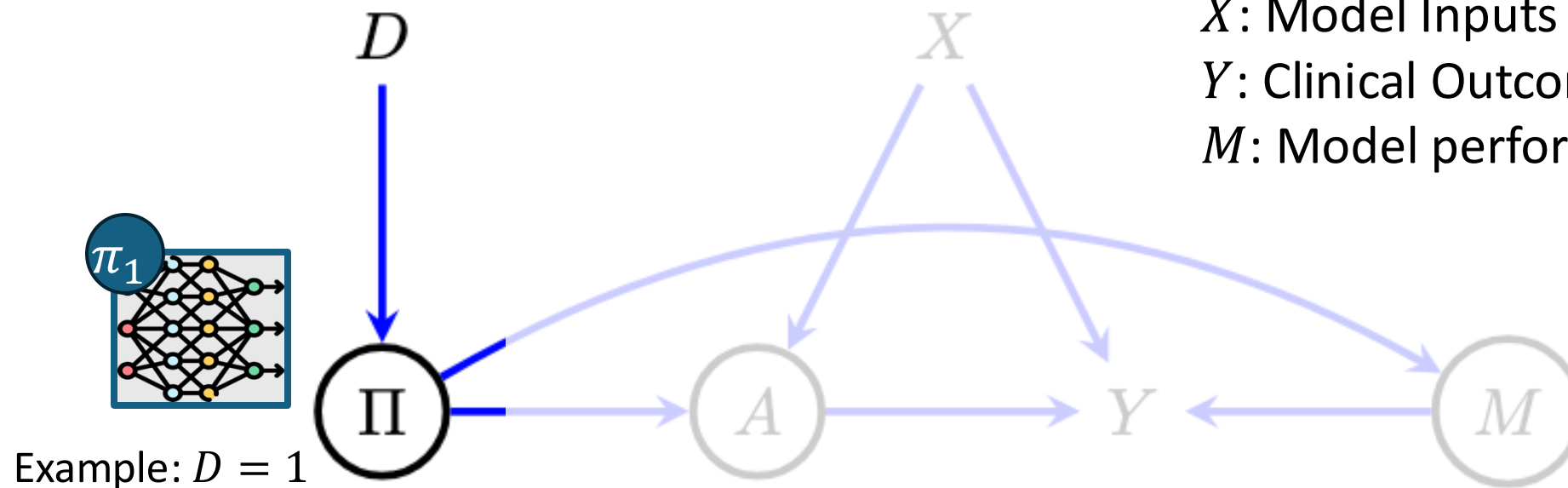
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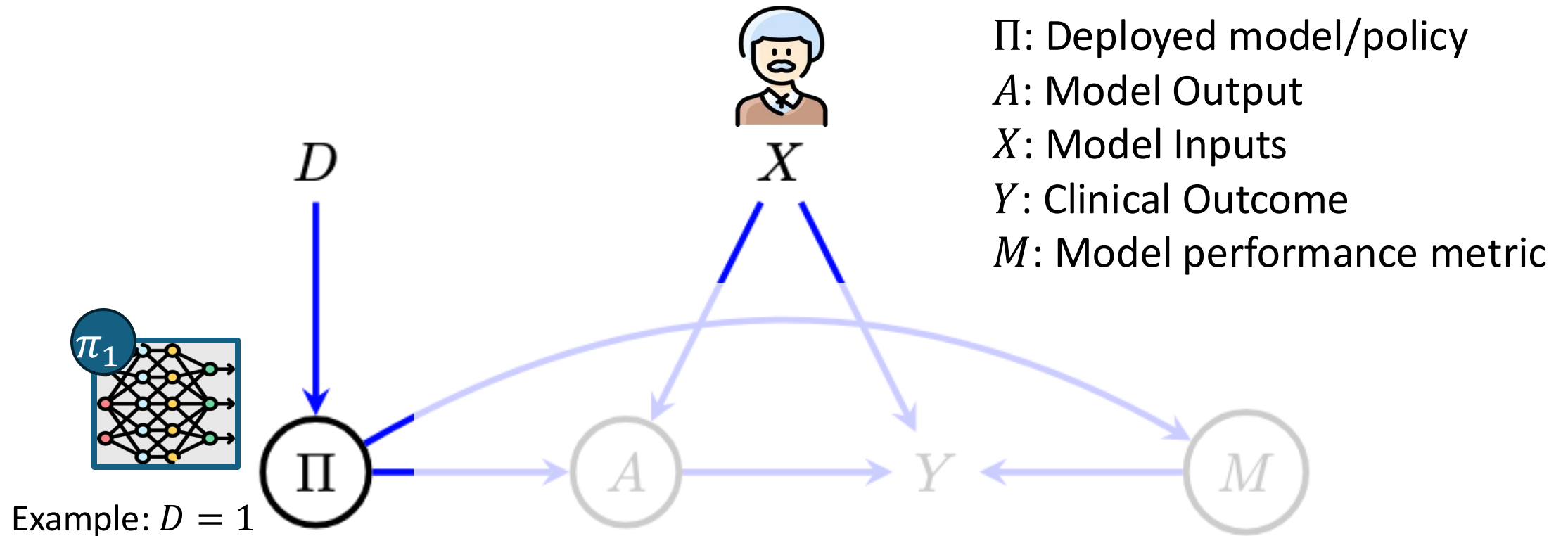
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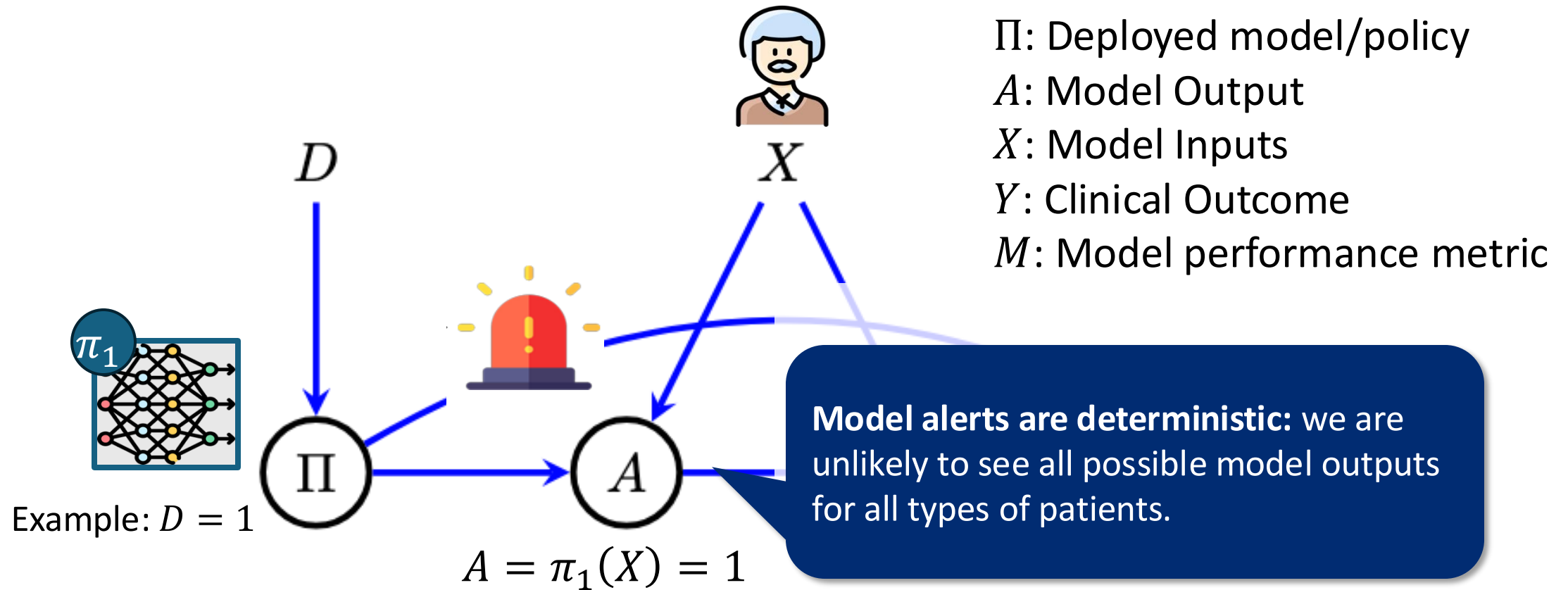
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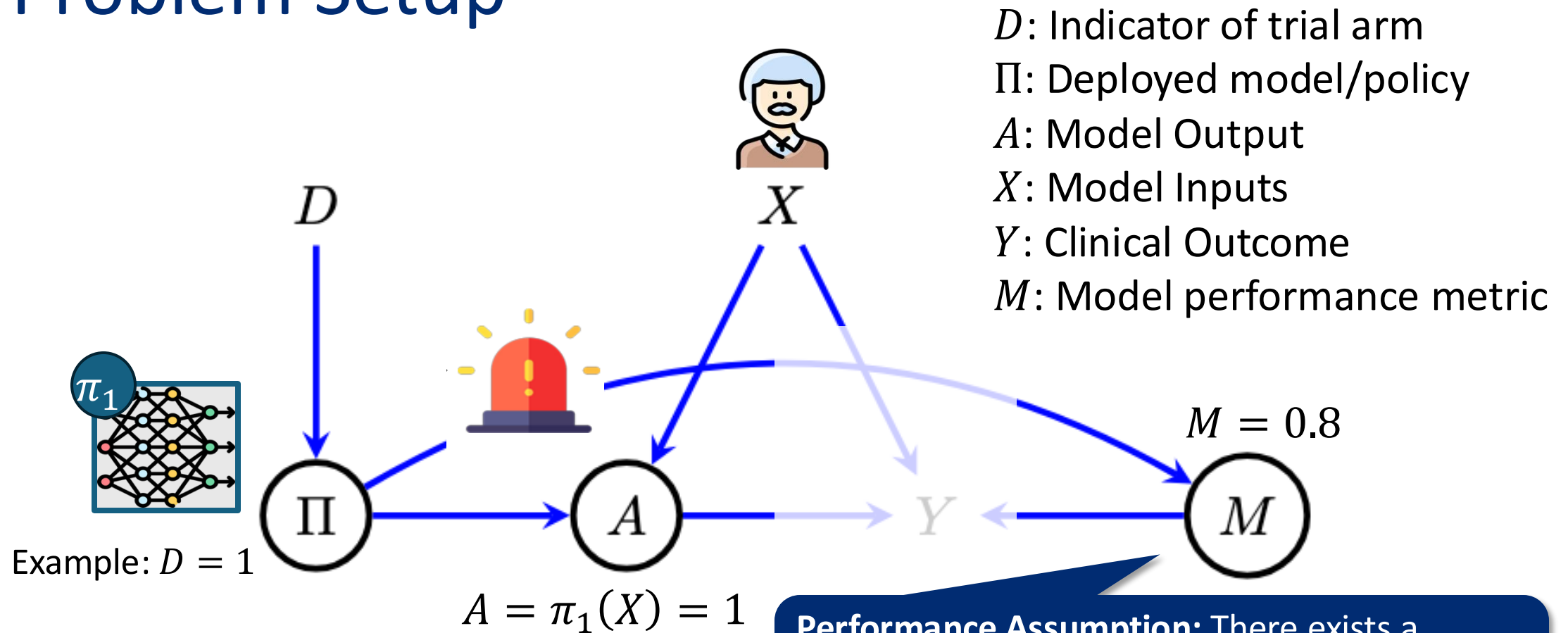
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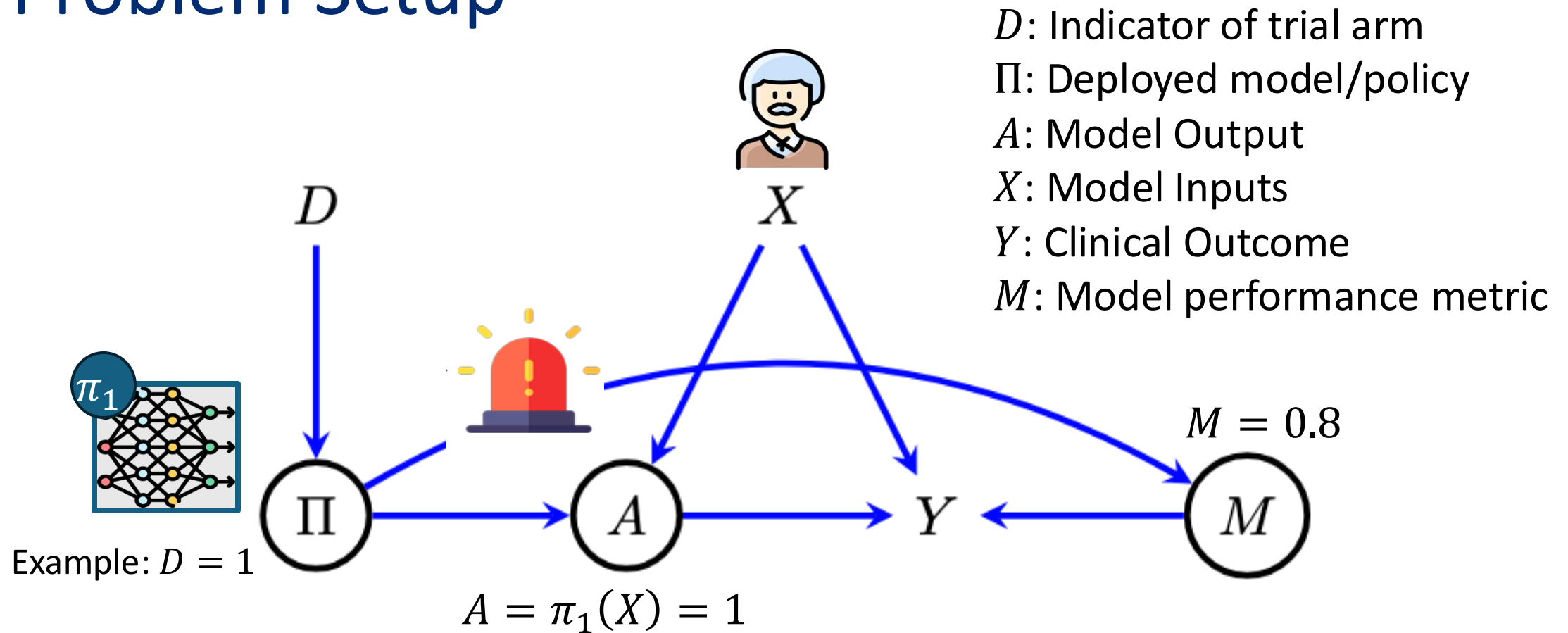
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Performance Assumption: There exists a computable metric that captures overall model performance / trust (e.g., false alarm rate).

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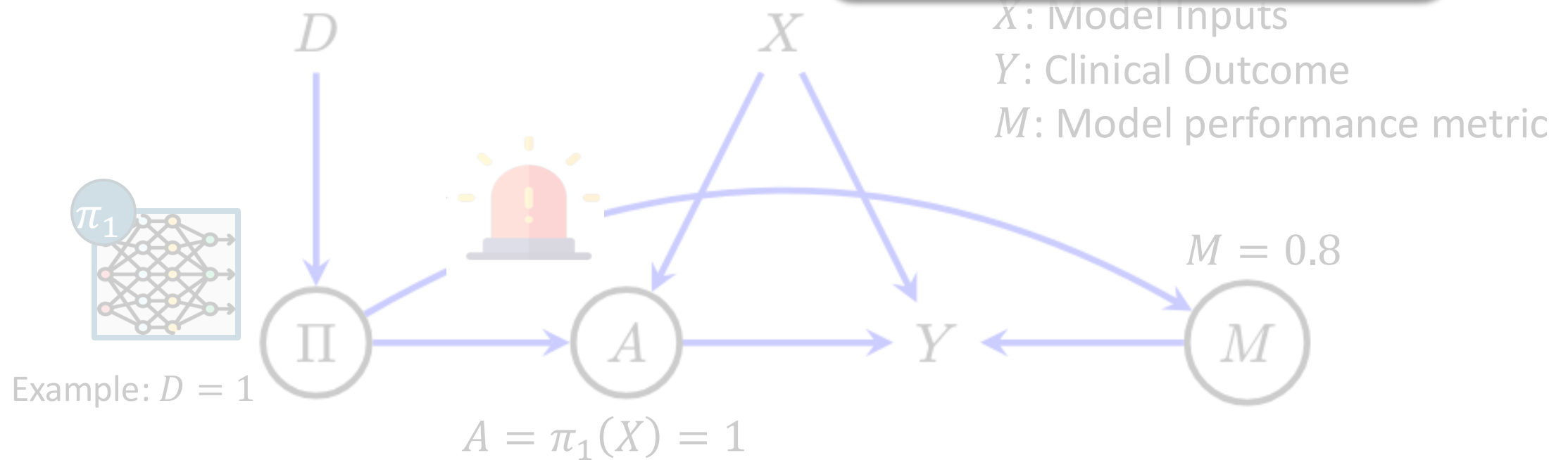


Assumed causal data-generating process

Problem Setup

Goal: Bound $E[Y(\pi_{new})]$, the expected outcome under model π_{new} .

Potential outcomes notation: the outcome that would have occurred had we counterfactually deployed the new model.

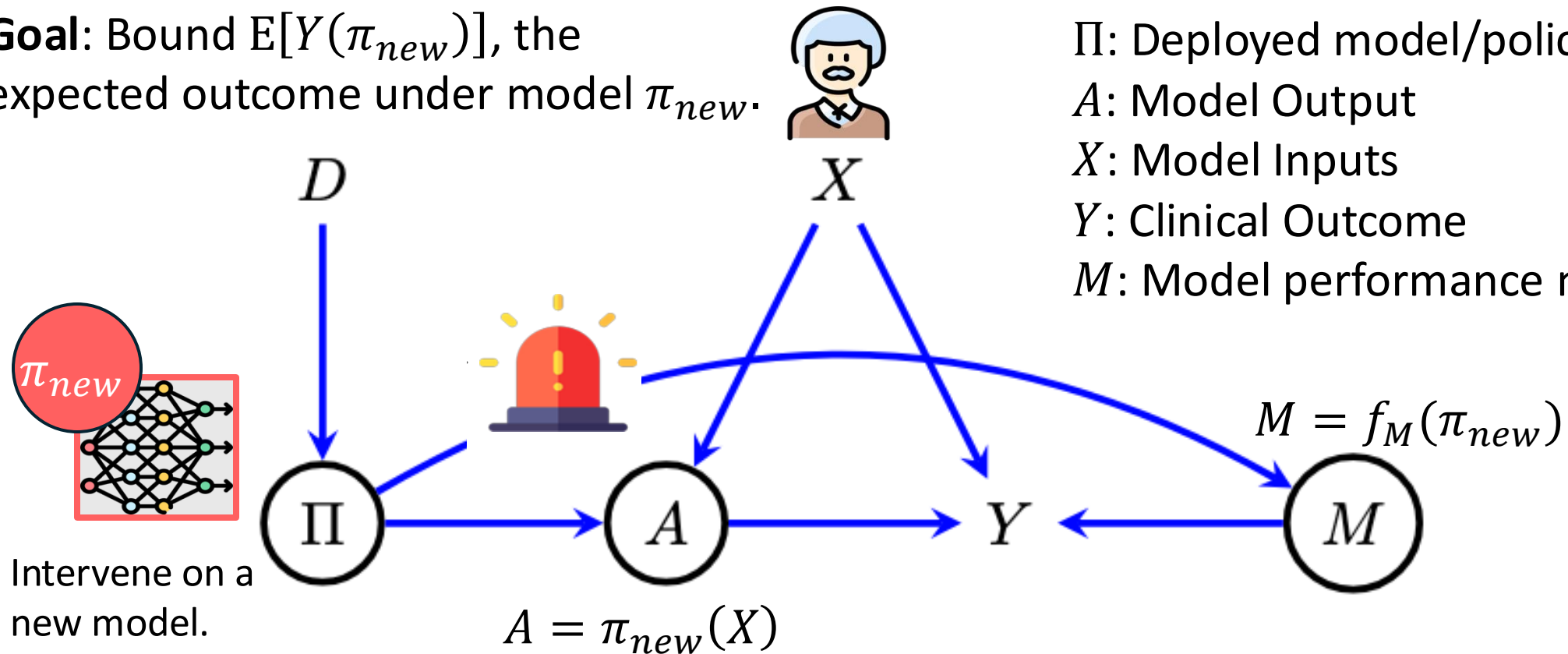


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Assumption 1: Performance Monotonicity

Potential outcomes are non-decreasing in model performance metric, i.e., if $m_i < m_j$ then for all $a \in \mathcal{A}$,

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This assumption has observable implications in the RCT if multiple models are trialed. Thus, it can be falsified by comparing two empirical means.

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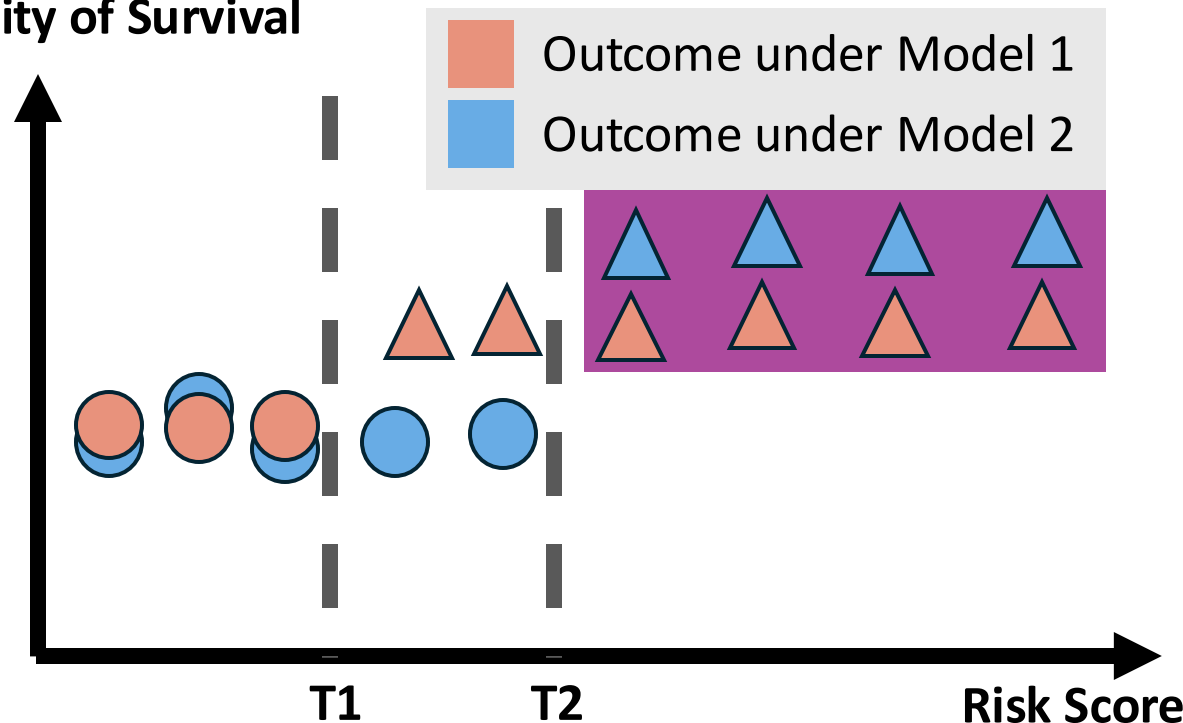
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Model 2 has a better performance metric than Model 1.

Is Assumption 1 consistent with data?



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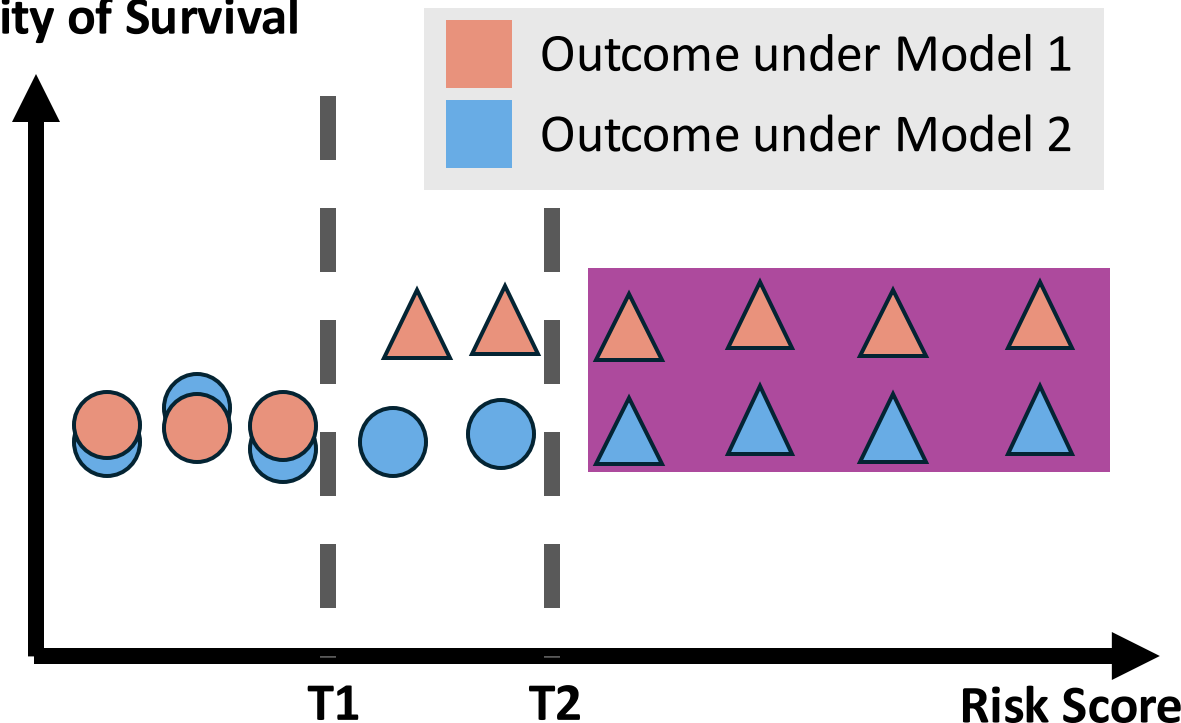
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The “control model” always outputs the neutral action (deferral, no alert, etc.). This assumption allows us to make use of control arm data.

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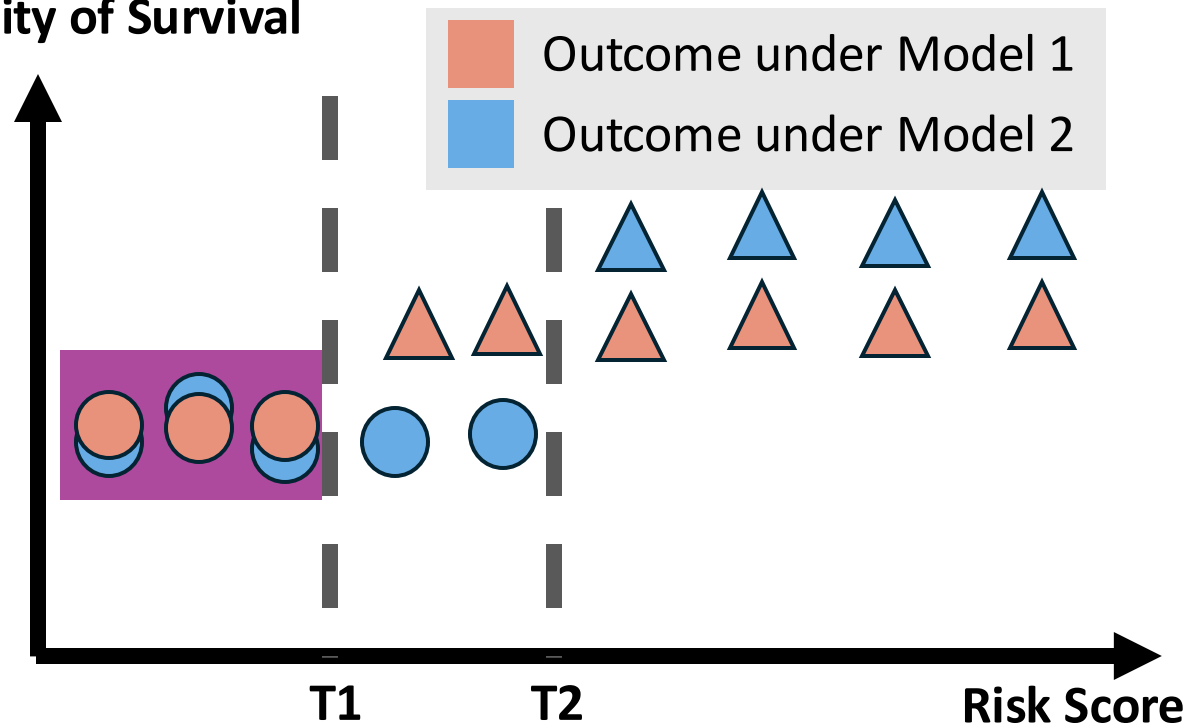
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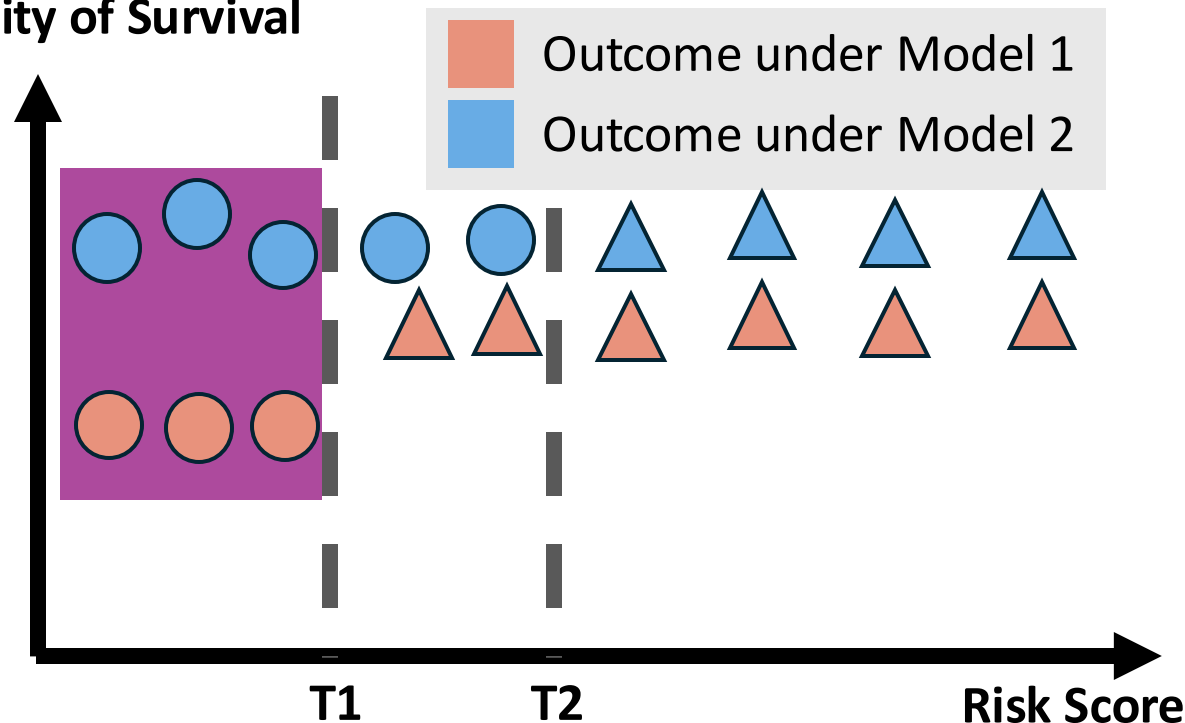
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There exists constants Y_{min} and Y_{max} such that $Y_{min} \leq Y \leq Y_{max}$.

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Boundedness is satisfied in practice with, for example, binary outcomes.

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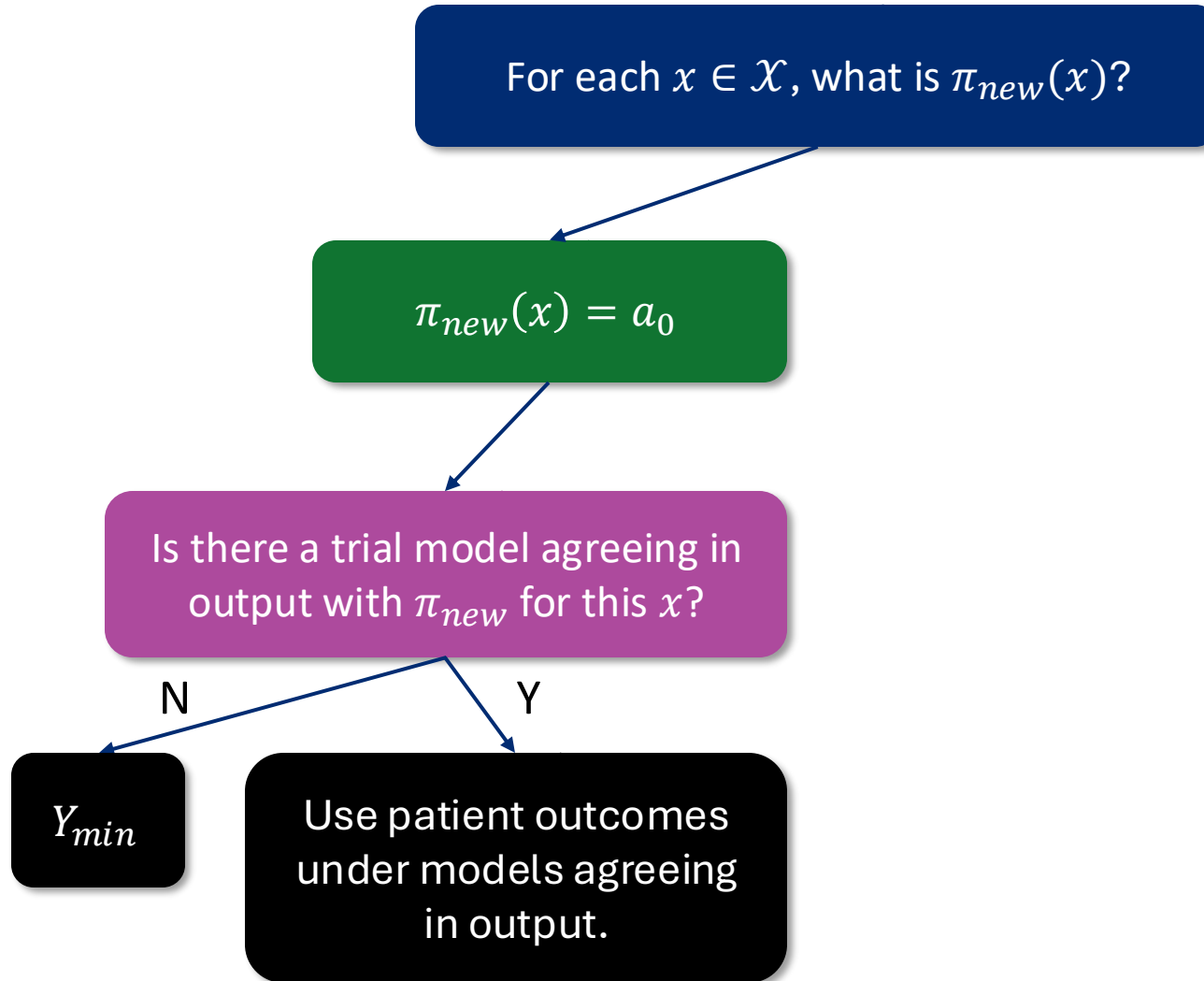
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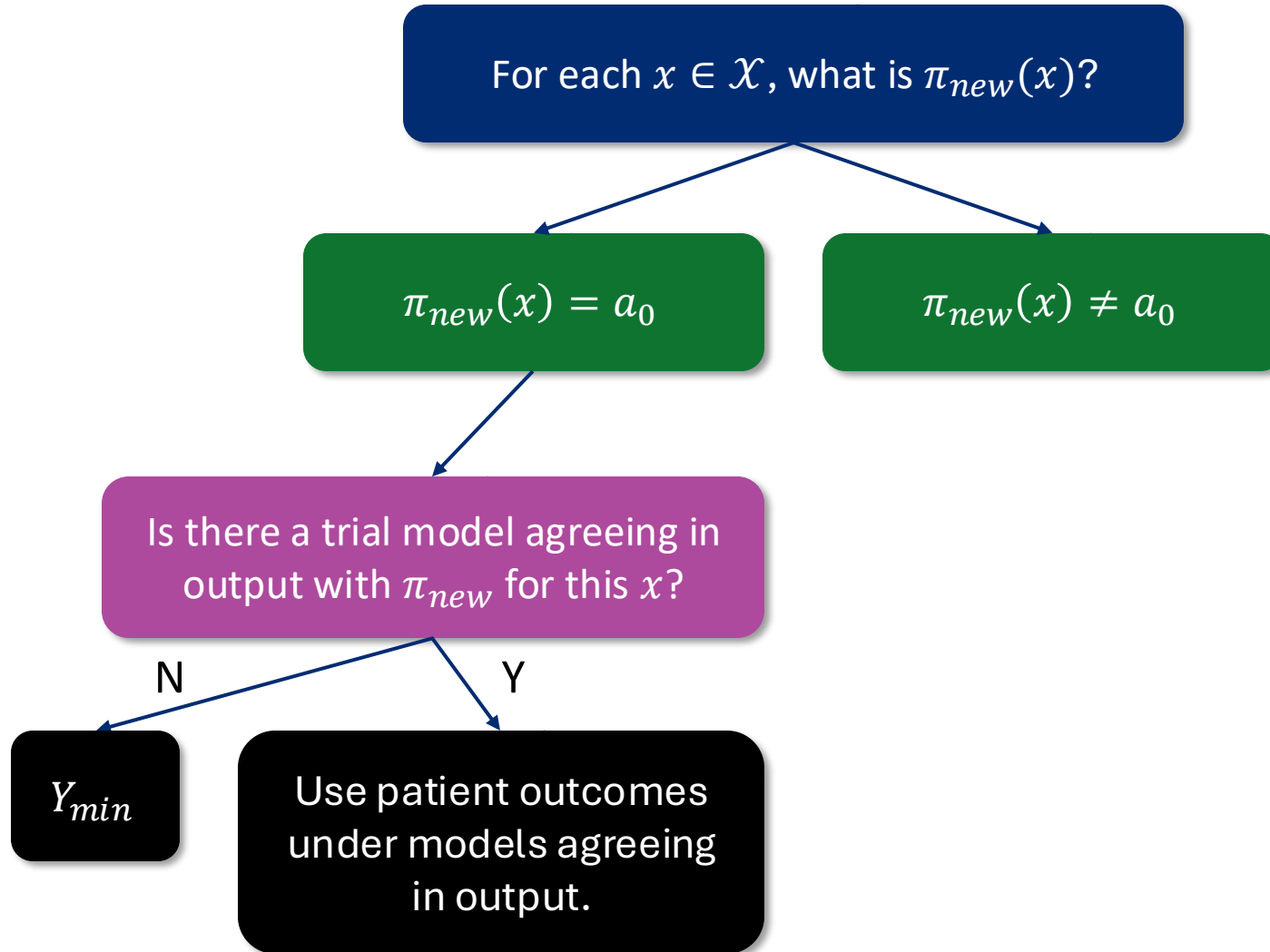
Y

Use patient outcomes under models agreeing in output.

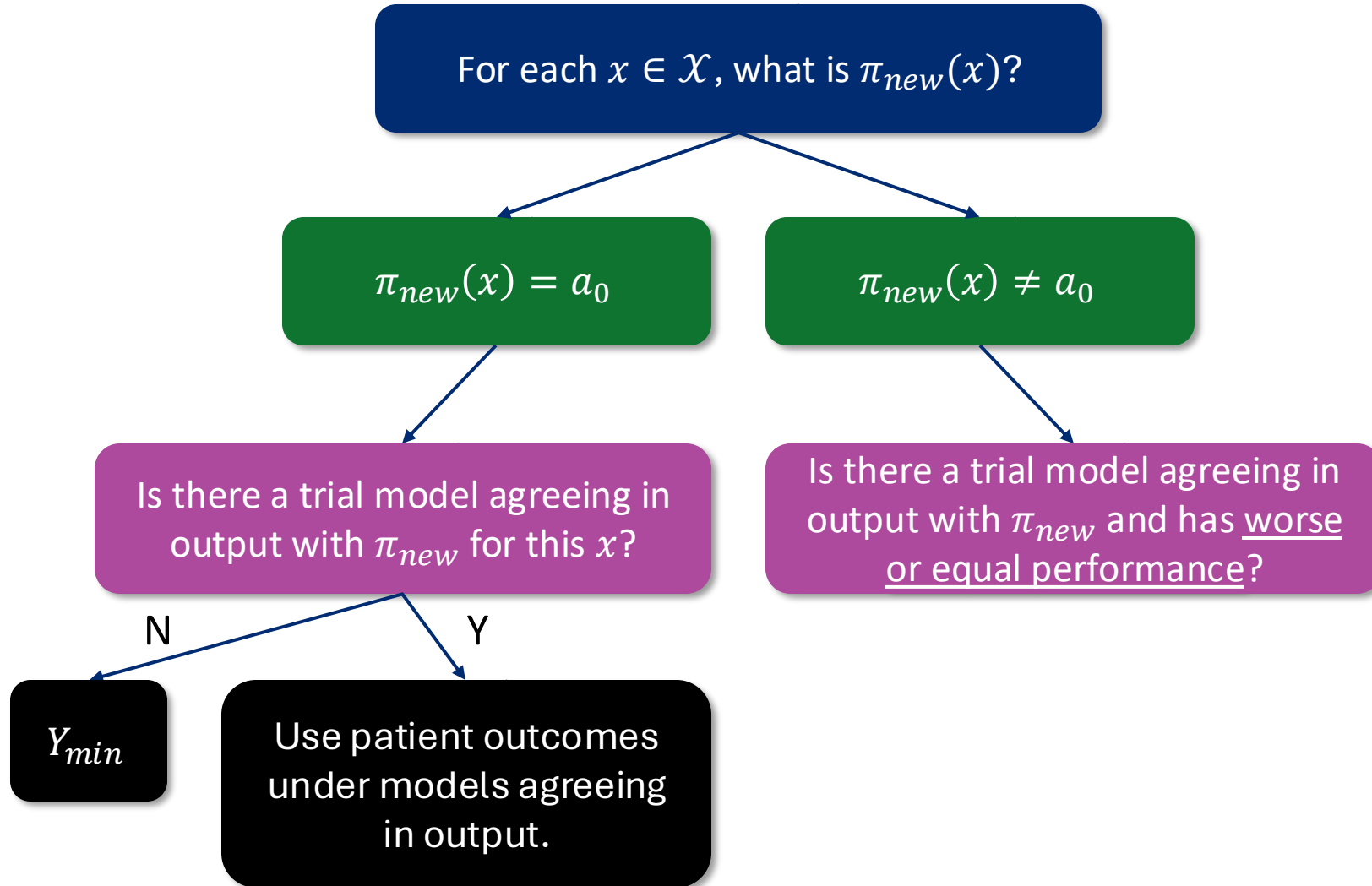
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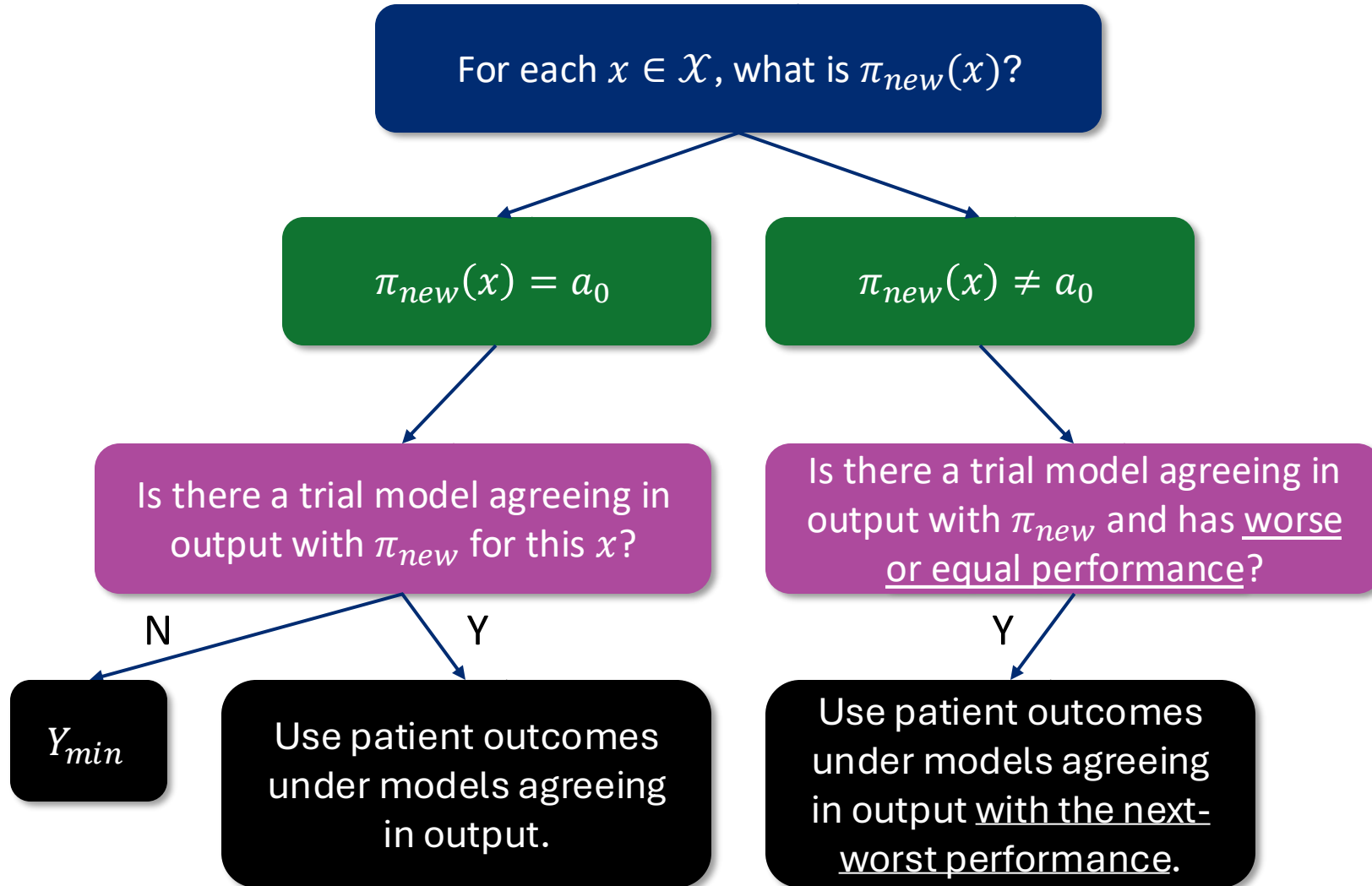
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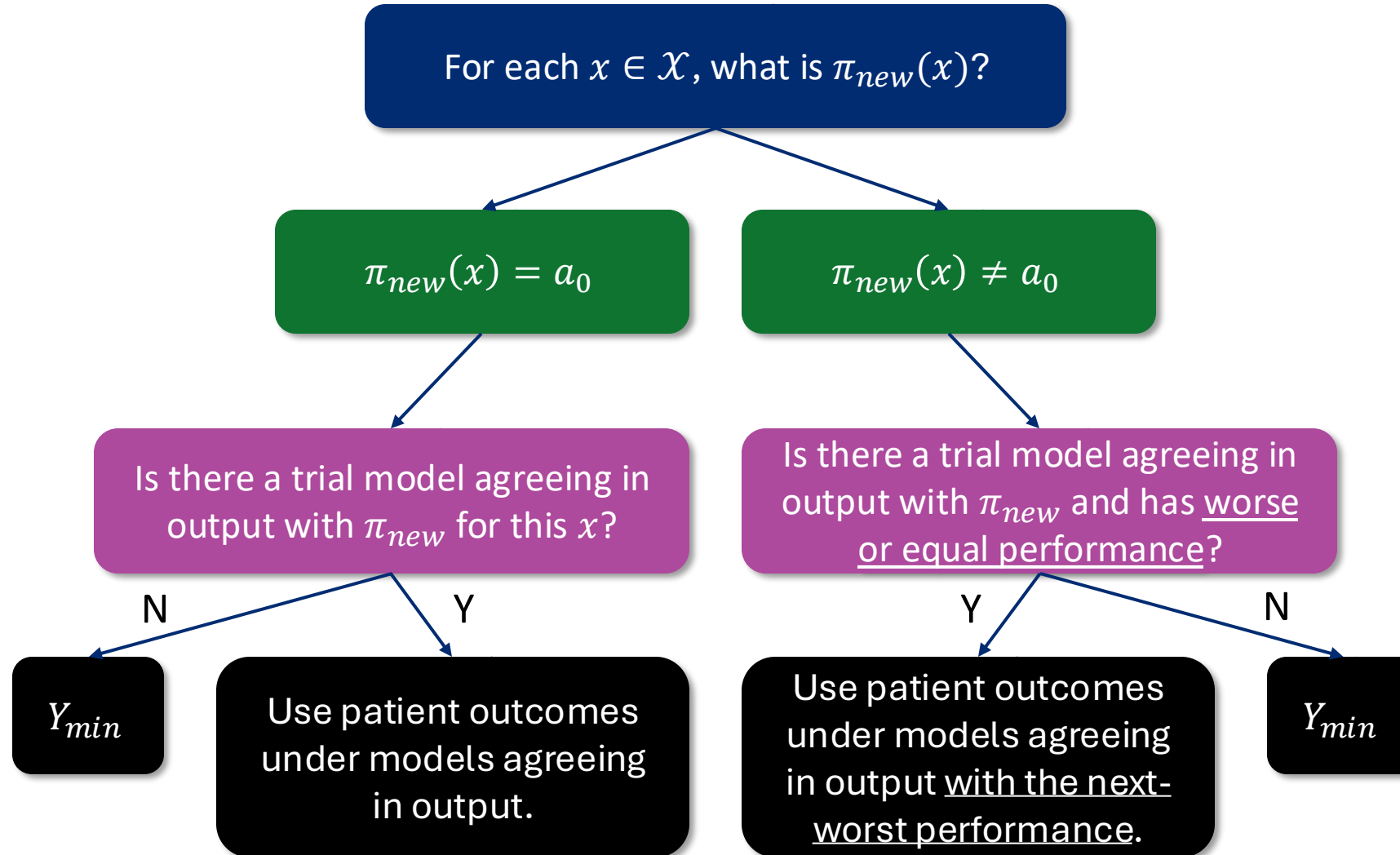
Lower Bound on Causal Impact



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Lower Bound on Causal Impact



Lower / Upper Bounds on Causal Impact

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Lower / Upper Bounds on Causal Impact

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- We give inverse-probability weighted (IPW) estimators for the bounds with asymptotically valid confidence intervals (Proposition 3.4).
- The more “similar” that the trialed models in the RCT are to the new model in coverage and performance metric, the tighter the bounds will be.

Summary

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- One implication of results: **trial multiple models in cluster RCTs**. This allows for falsification of assumptions and alleviates challenges related to coverage and performance.
- Potential use case: **bounding causal impacts of model updates** before trialing new model updates in RCTs.
- A step towards reliable re-use of RCT data evaluating ML models.

Thank you for your attention!

- Please join us at our poster this afternoon from 16:00-18:30!

Please scan the QR code for the
arXiv link to our paper.



Backup Slides

Inverse Probability Weighted-Style Estimators

$$\psi_L(Y, X, \Pi) := \begin{cases} Y \cdot \frac{\mathbf{1}\{\Pi \in \tilde{\Pi}_{\leq}^e(X)\}}{P(\Pi \in \tilde{\Pi}_{\leq}^e(X))}, & \text{if } \tilde{\Pi}_{\leq}^e(X) \neq \emptyset, \pi_e(X) \neq a_0 \\ Y_{min}, & \text{if } \tilde{\Pi}_{\leq}^e(X) = \emptyset, \pi_e(X) \neq a_0 \\ Y \cdot \frac{\mathbf{1}\{\Pi \in \Pi^e(X)\}}{P(\Pi \in \Pi^e(X))}, & \text{if } \Pi^e(X) \neq \emptyset, \pi_e(X) = a_0 \\ Y_{min}, & \text{if } \Pi^e(X) = \emptyset, \pi_e(X) = a_0 \end{cases}$$

Notation: Partitions of Model Sets

Definition 3.1 (Policy/Model Sets). For each value of $x \in \mathcal{X}$, we define the sets of trialed policies/models (possibly none) that agree with $\pi_e(x)$ and subsets of this set based on the performance characteristics of those trialed models⁵.

① Subset of models that agree in output with the new model for a patient x .

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Randomized Controlled Trials (RCTs) help us compare between two scenarios

Compare no deployment of ML model vs. deployment of ML model.

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Patient



Actions



Outcome



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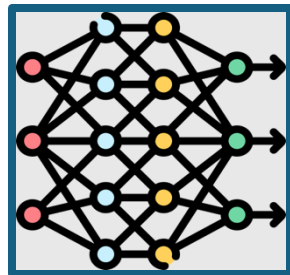
Patient

Model

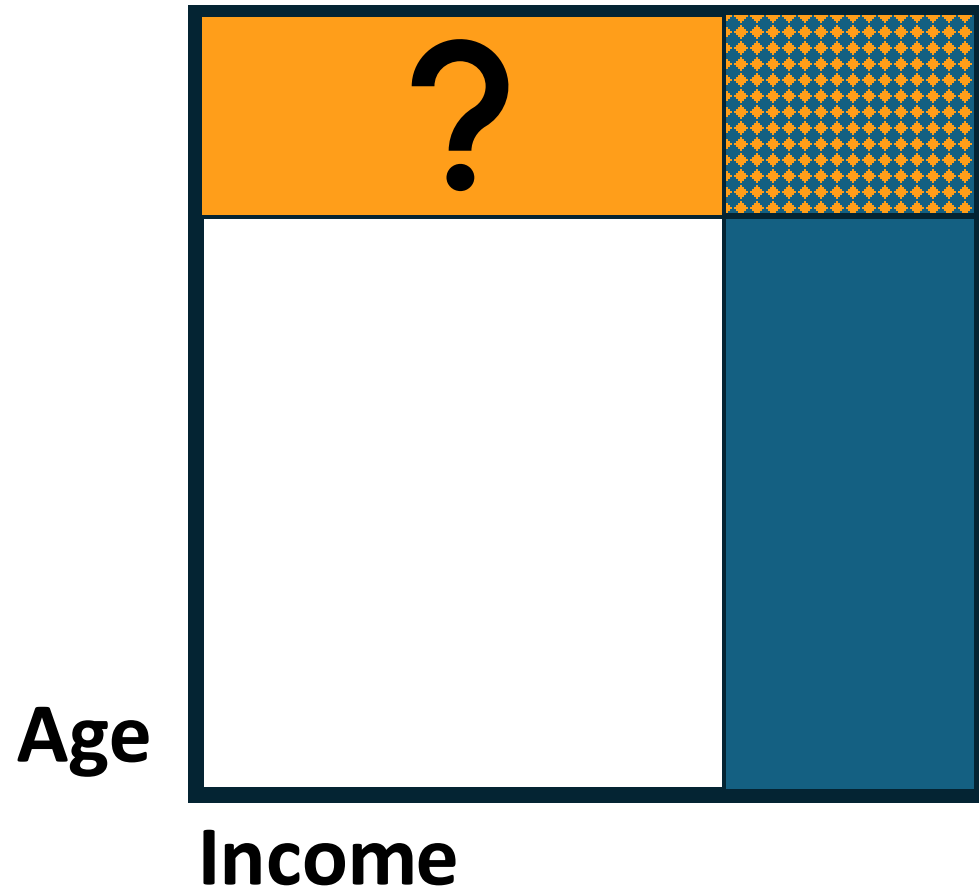
Output

Actions

Outcome

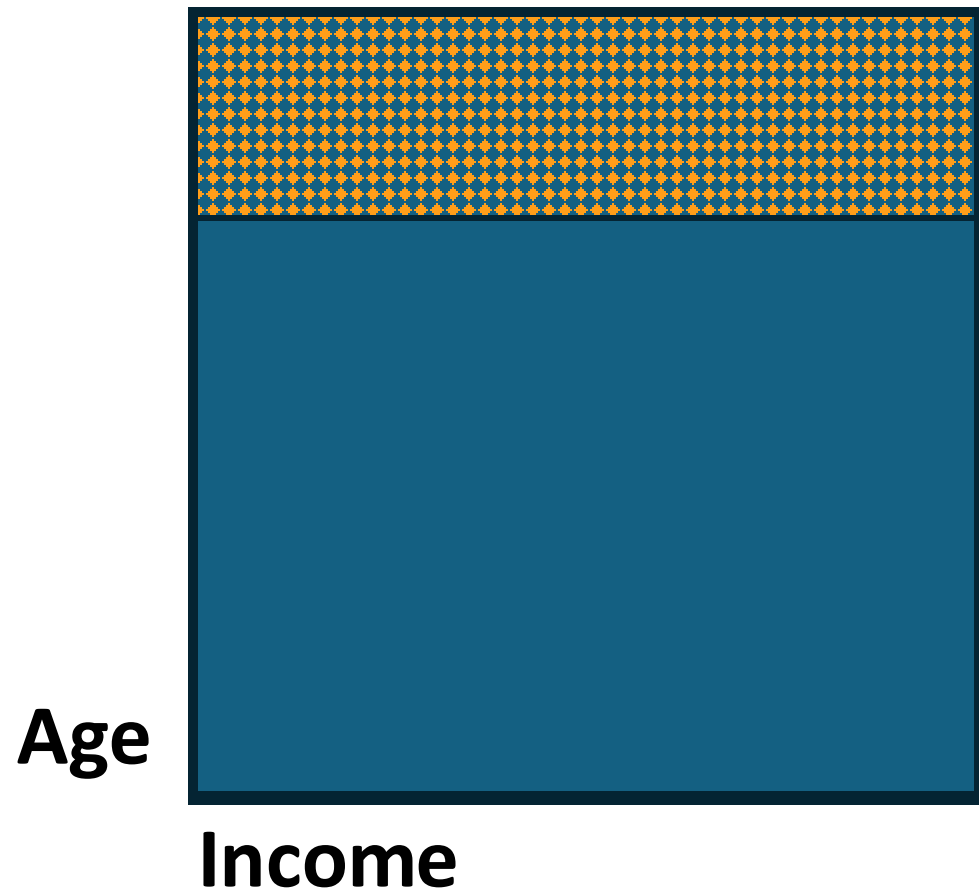


Why Require the Performance Assumption?



Recall the coverage challenge.

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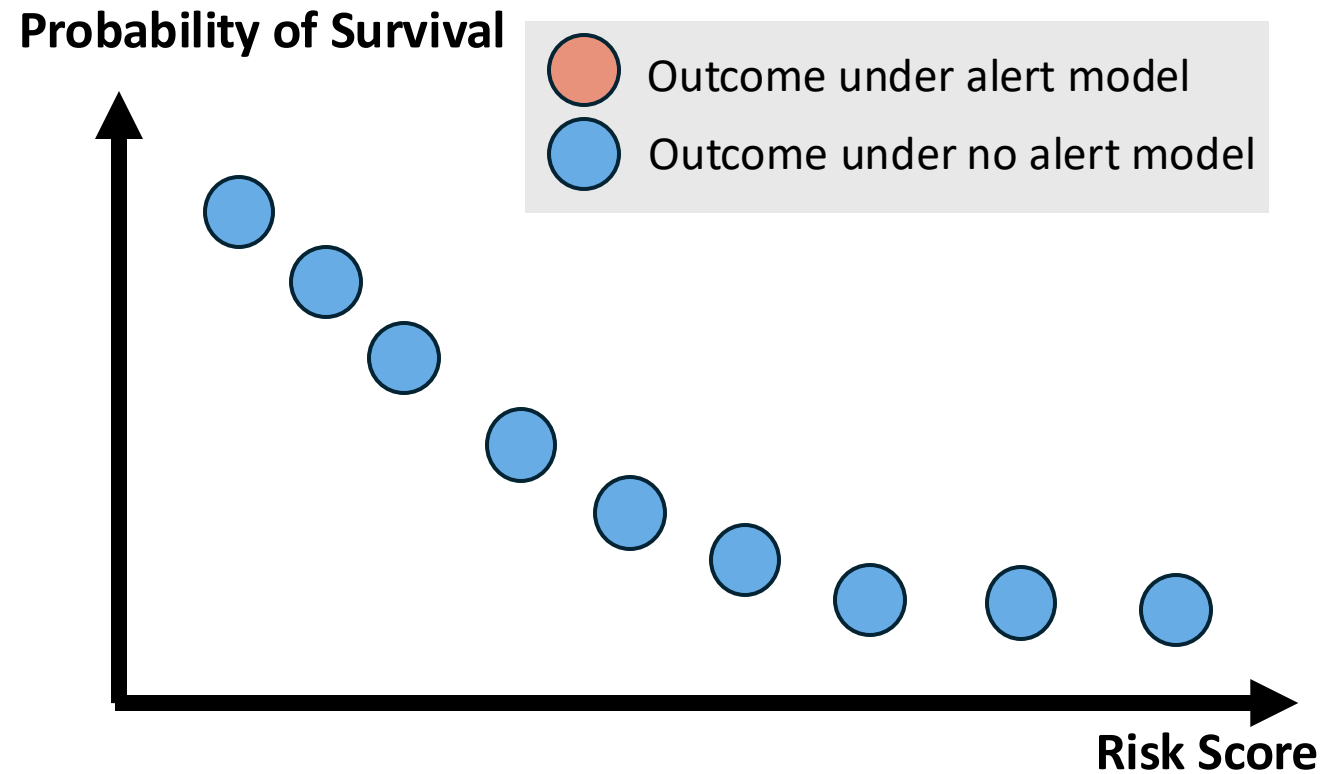
A simple solution: have the trained model (blue) cover the whole square.

Why Require the Performance Assumption?

- Why is trialing a model that always alerts and a model that never alerts (the control arm) a bad idea?

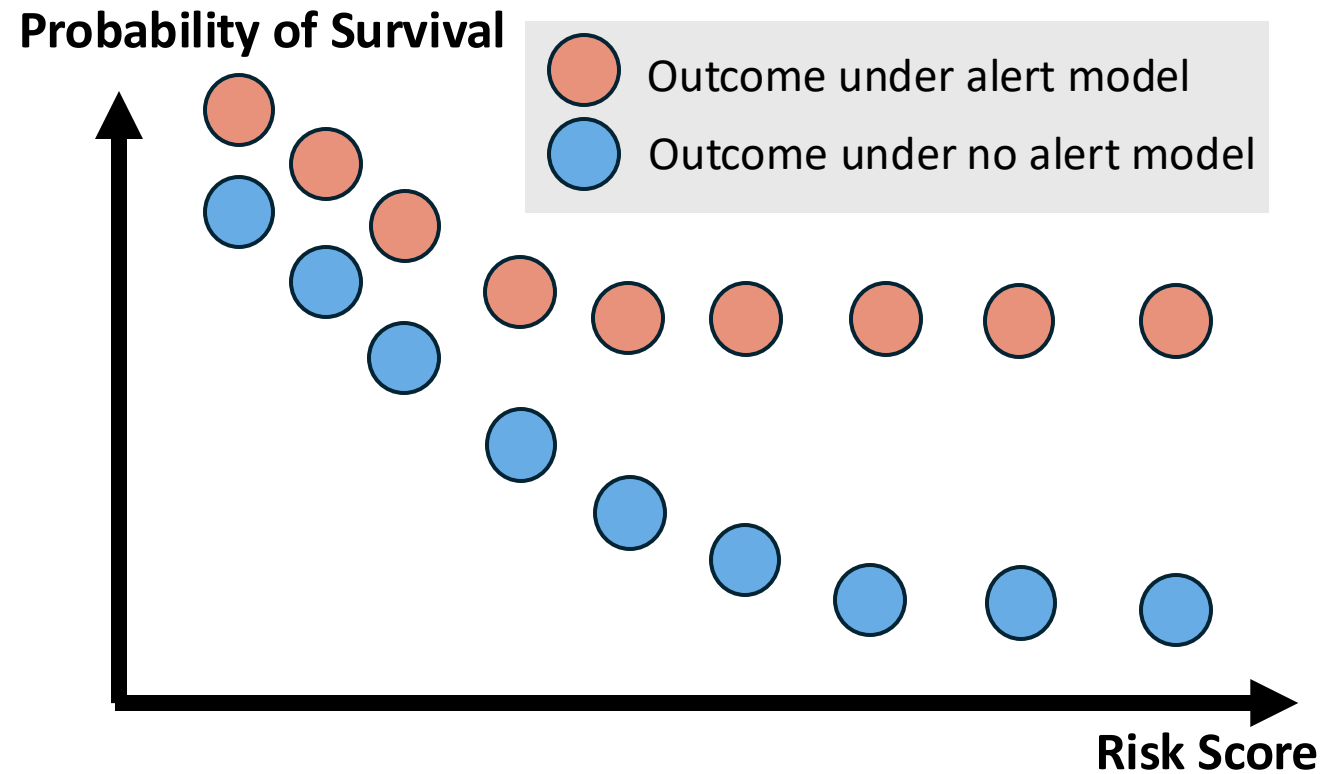
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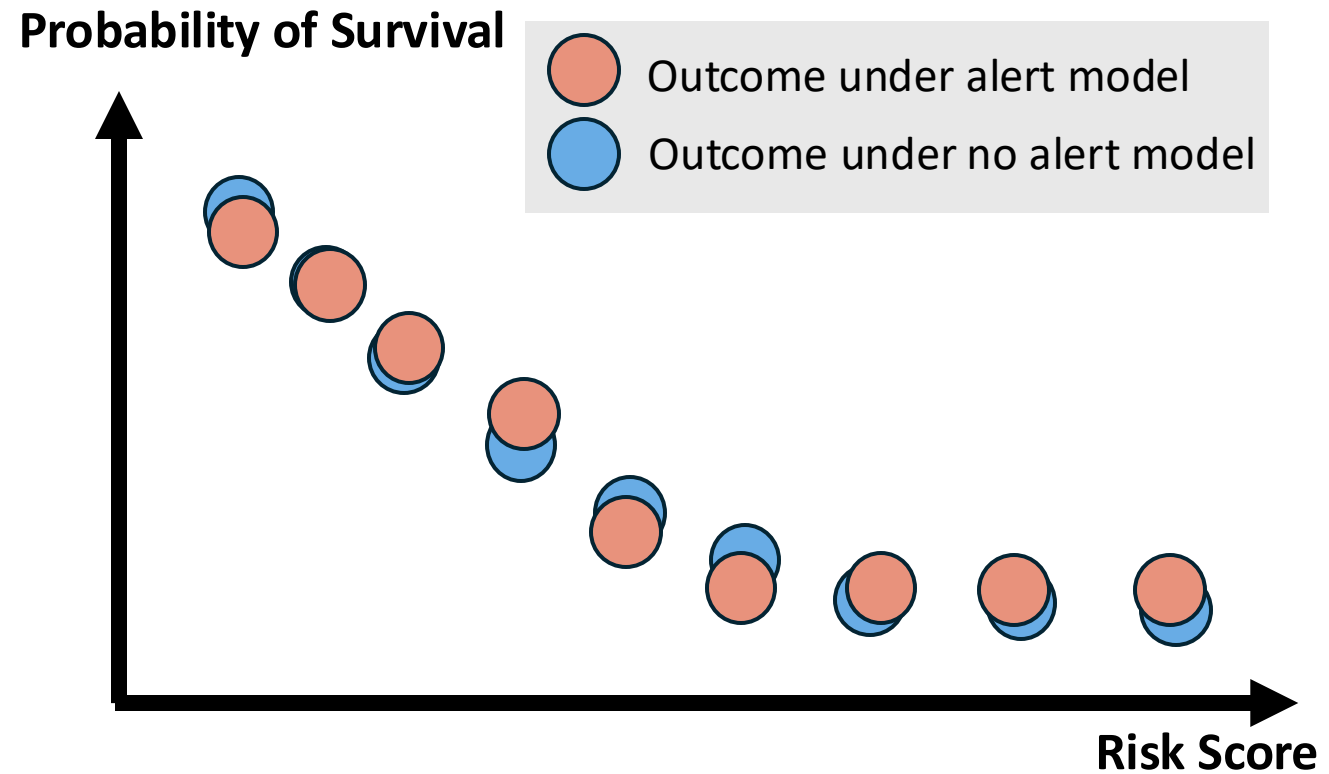
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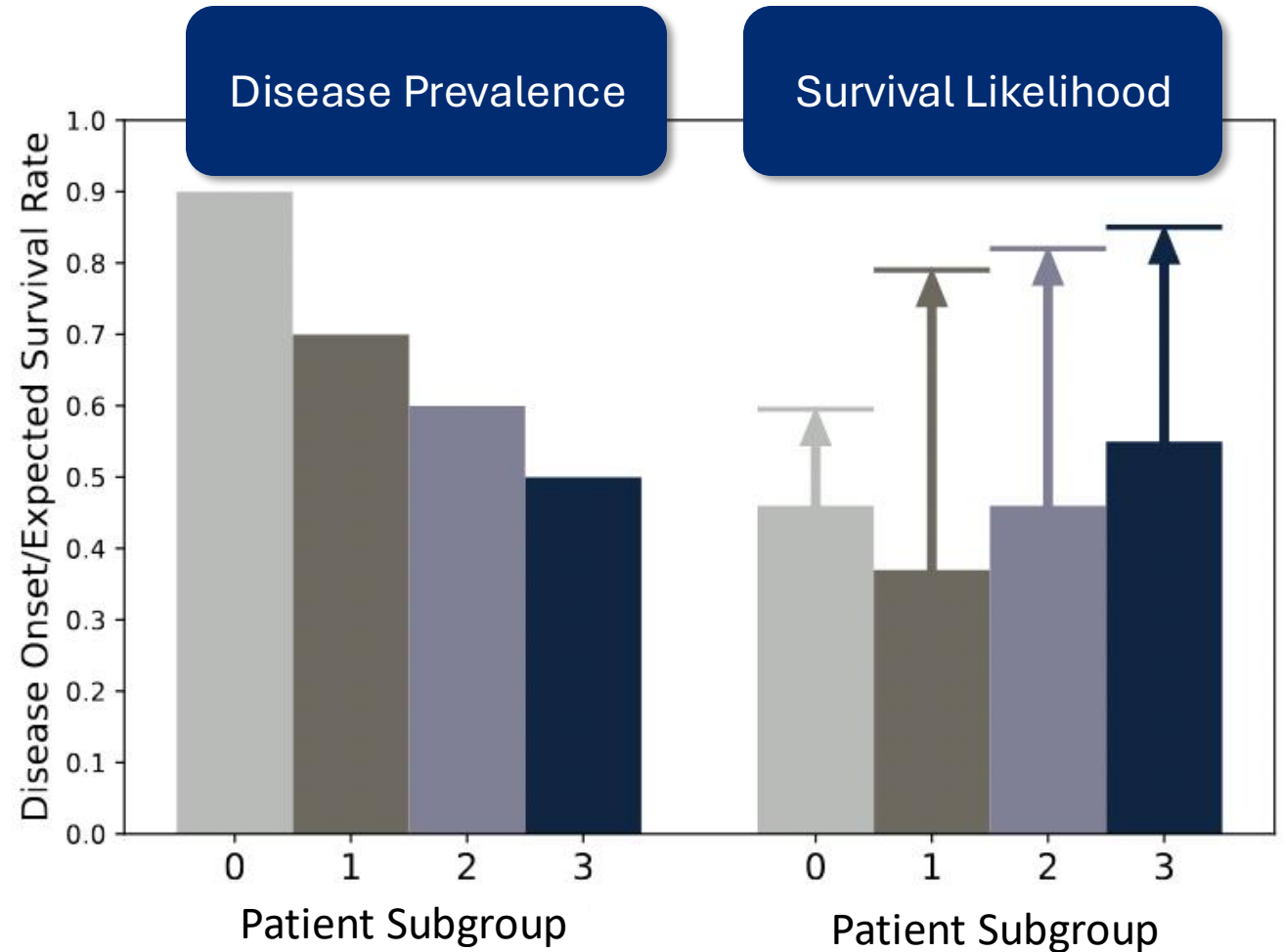
- Why is trialing a model that always alerts and a model that never alerts (the control arm) a bad idea?
- This “always alert” model will likely have minimal impact due to its poor performance.



Synthetic Simulation Study

Setup

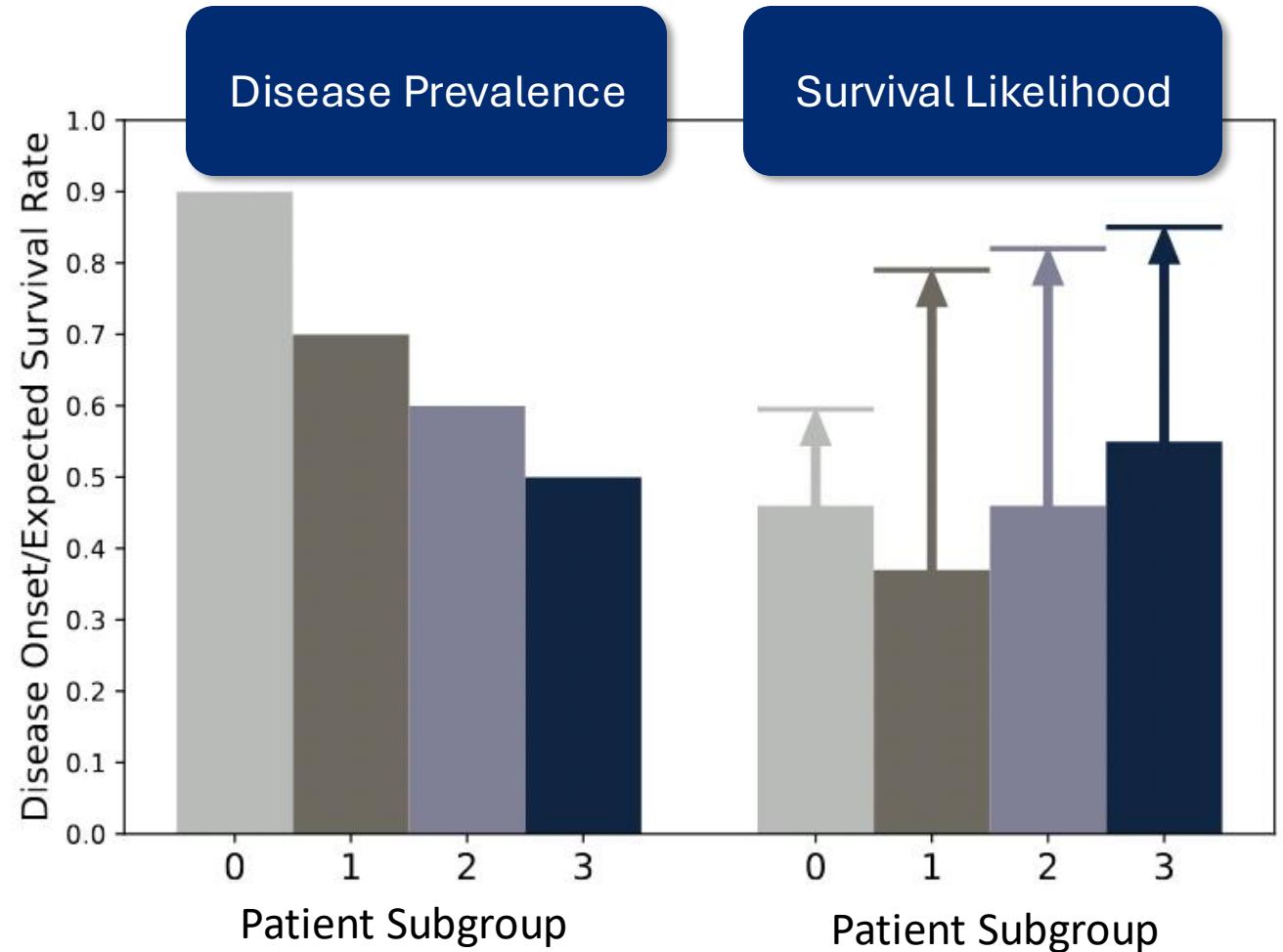
- Four types of patients with varying likelihoods of developing disease and survival rates.



Synthetic Simulation Study

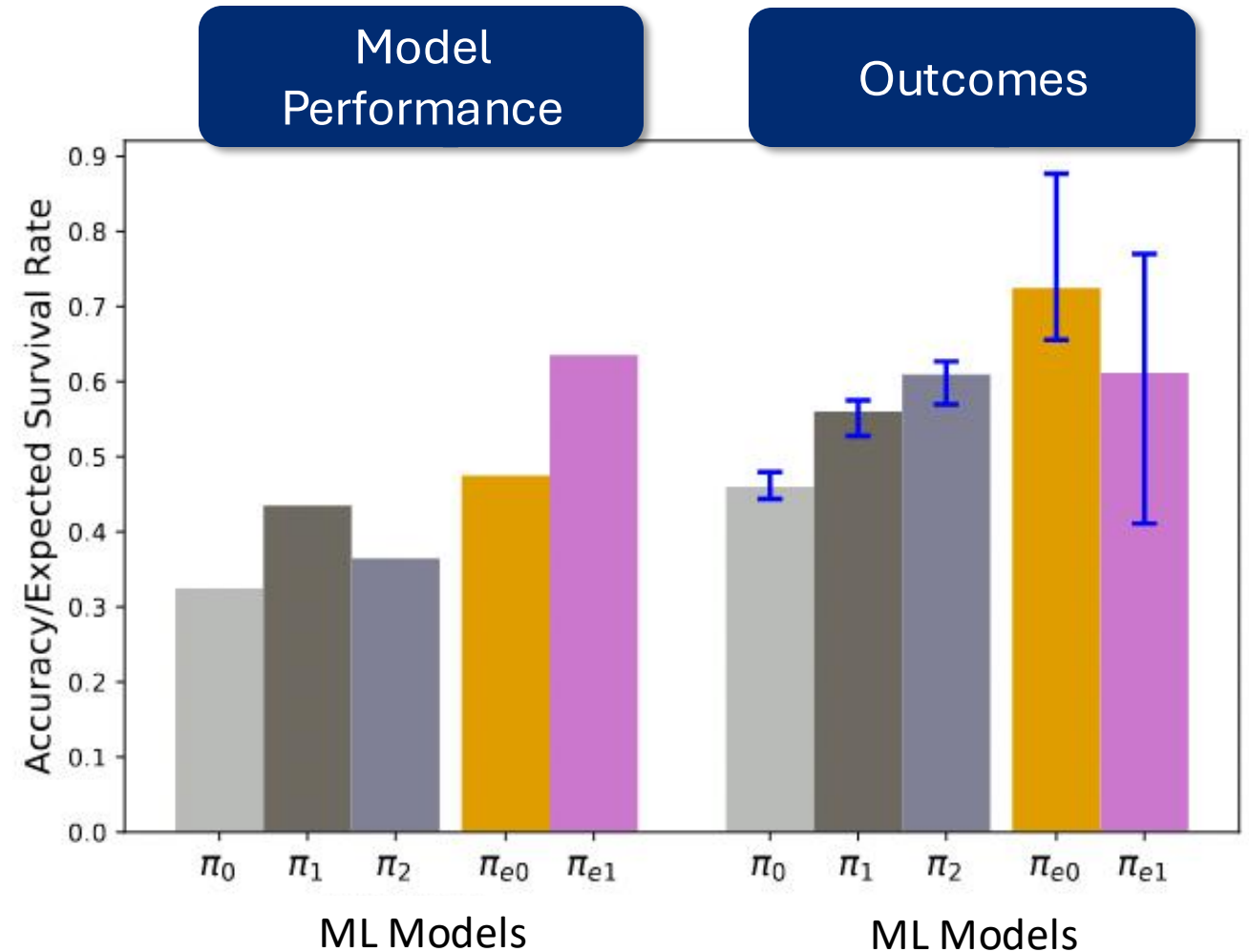
Setup

- Four types of patients with varying likelihoods of developing disease and survival rates.
- Raising alerts on the highest-risk (“most obvious”, $X=0$) patients is less helpful than raising alerts on other patients.



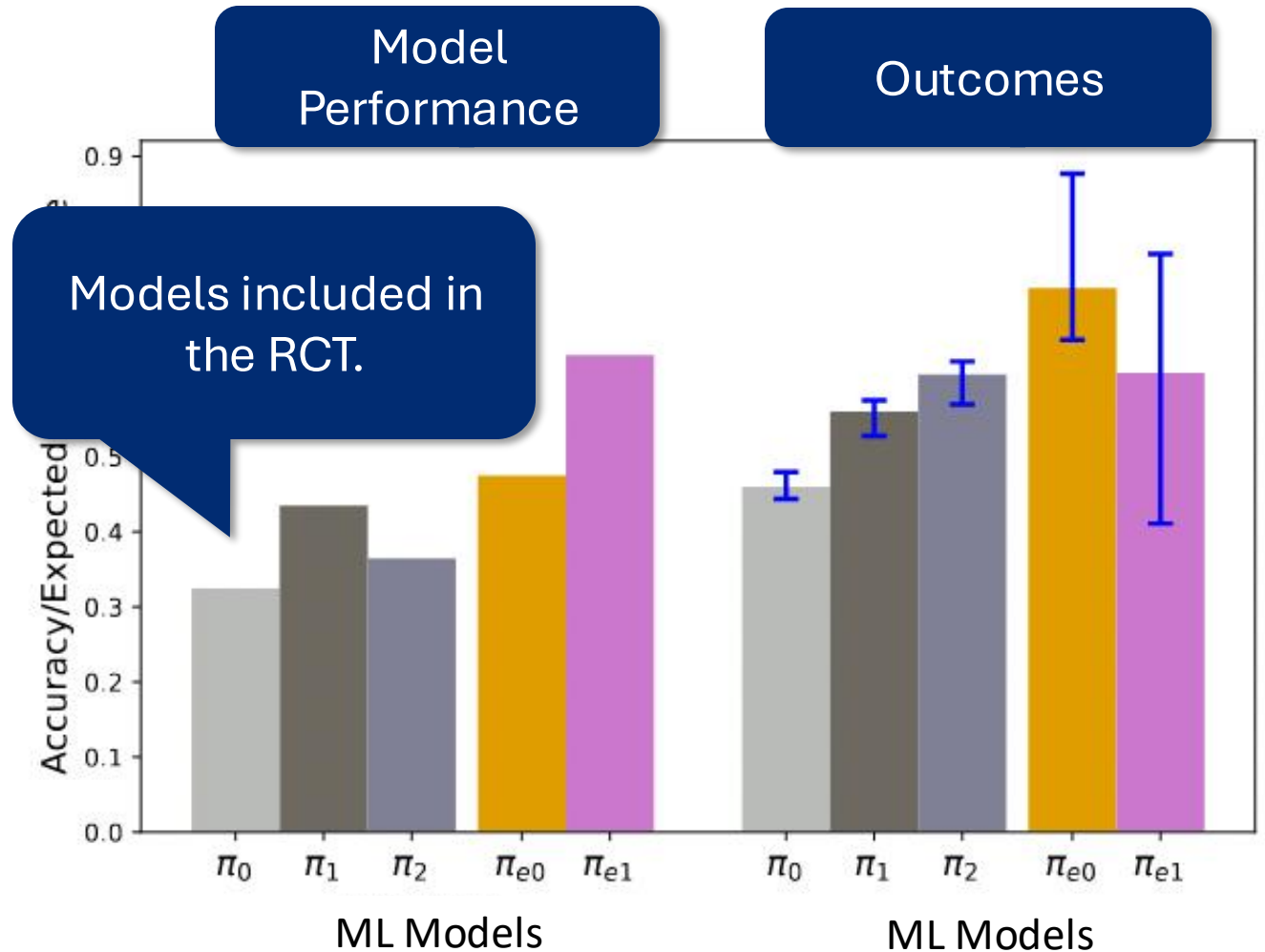
Synthetic Simulation Study

Results



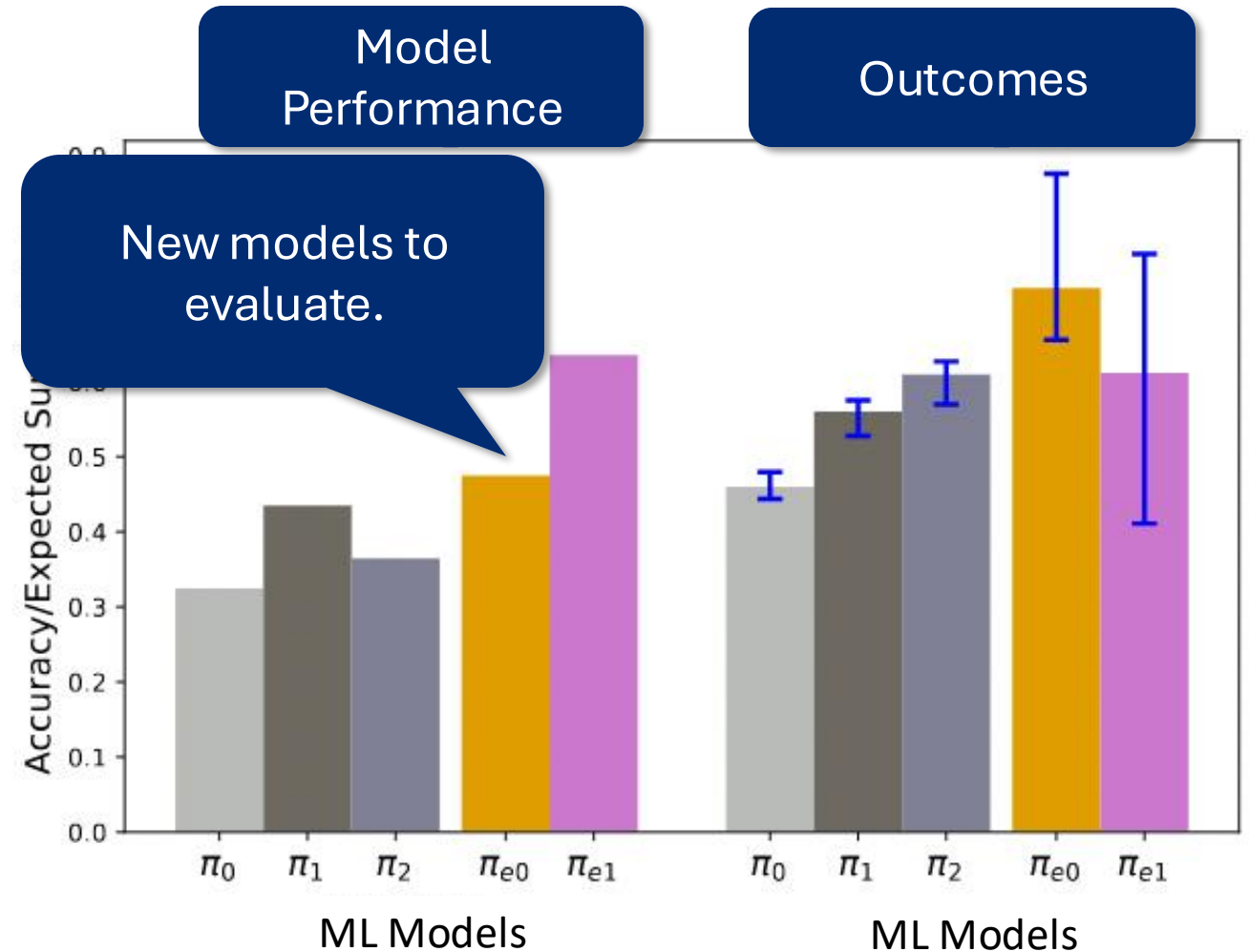
Synthetic Simulation Study

Results



Synthetic Simulation Study

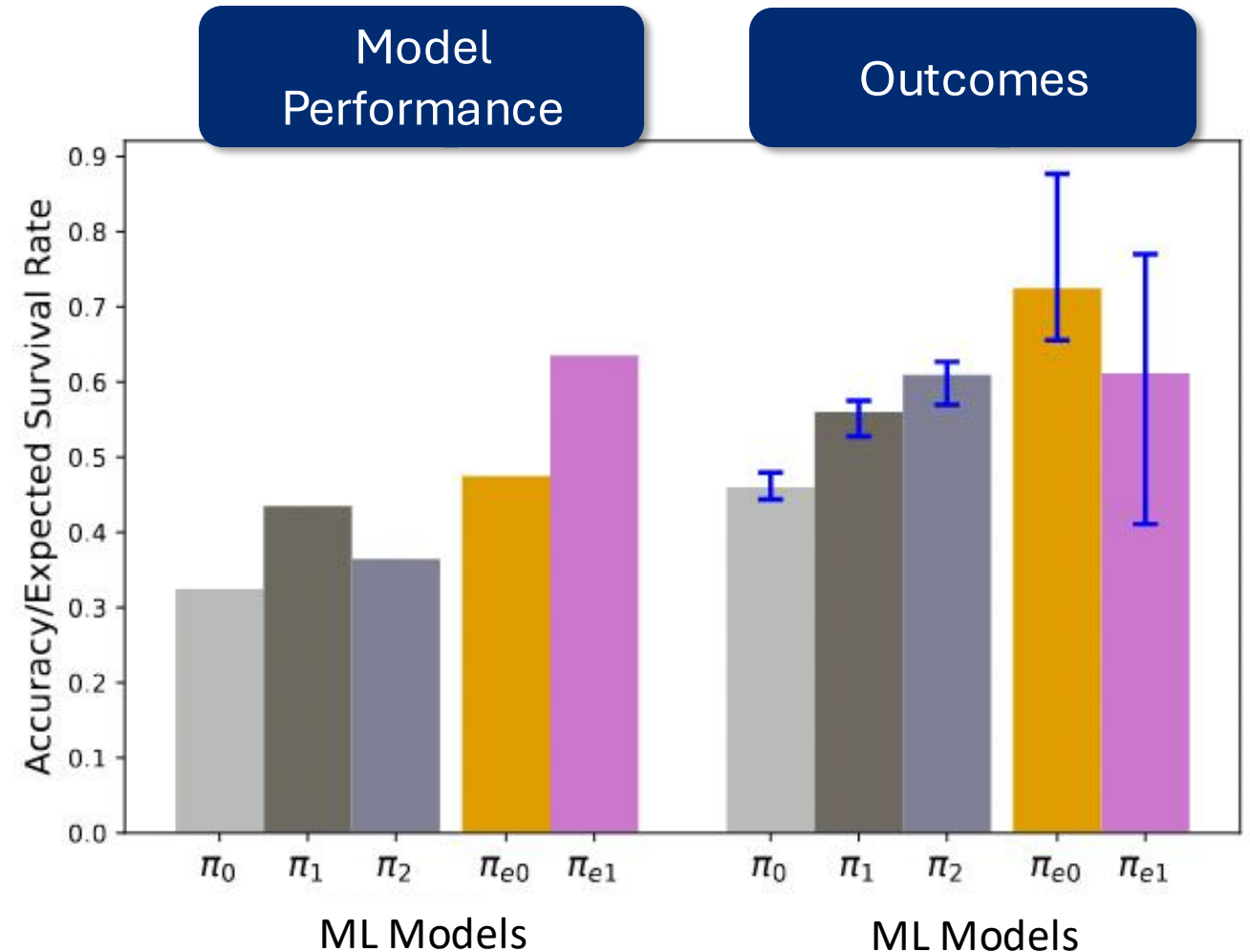
Results



Synthetic Simulation Study

Results

- Model performance is the raw accuracy of the model in predicting disease onset.
- Bars indicate ground truth, and intervals indicate statistical uncertainty.

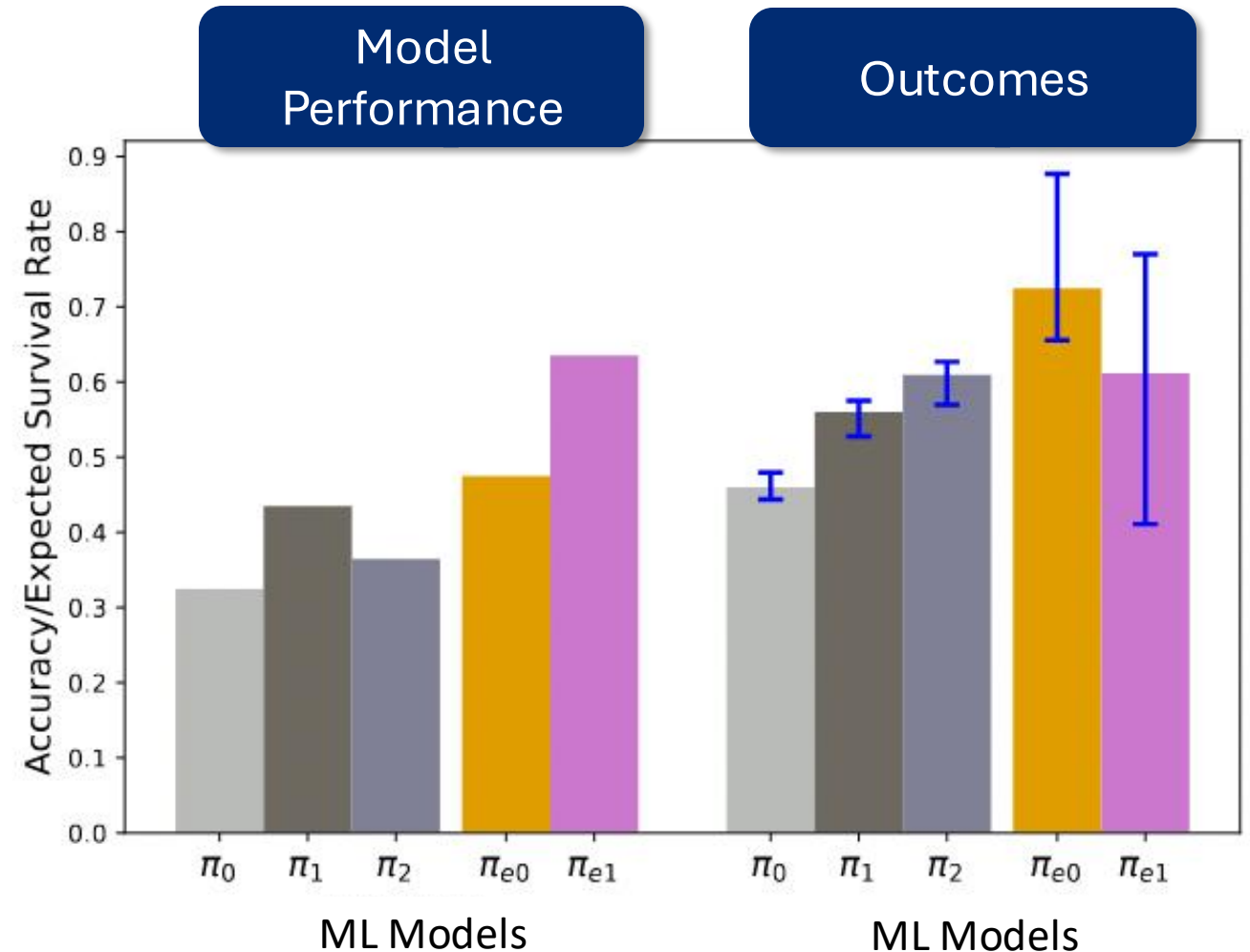


Synthetic Simulation Study

Results

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Model accuracy is not indicative of causal impact.



Machine Learning (ML) Models as Medical Devices

Artificial intelligence and machine learning models are increasingly deployed in high-risk domains such as healthcare.

Artificial Intelligence and Machine Learning in Software as a Medical Device

Artificial intelligence (AI) and machine learning (ML) technologies have the potential to transform health care by deriving new and important insights from the vast amount of data generated during the delivery of health care every day. Medical device manufacturers are using these technologies to innovate their products to better assist health care providers and improve patient care. The complex and dynamic processes involved in the development, deployment, use, and maintenance of AI technologies benefit from careful management throughout the medical product life cycle.

Need for More RCTs of ML/AI Models



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EDITORIAL

We Need More Randomized Clinical Trials of AI

David Ouyang , M.D.,¹ and Joseph Hogan , Sc.D.²

Received: September 5, 2024; Accepted: September 10, 2024; Published: October 18, 2024

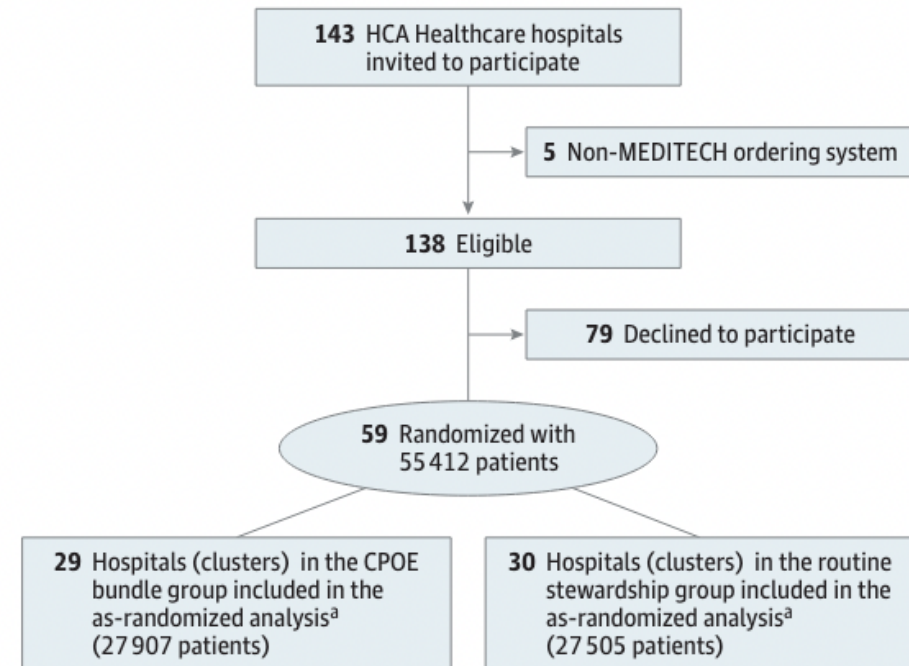
Abstract

In the first prospective clinical trial of artificial intelligence (AI) assistance in stress echocardiography, there was no difference in diagnostic accuracy between AI assistance and standard-of-care assessment. There is significant value in conducting prospective clinical trials of AI, and there are lessons on implementation to be learned from this study.

Recent RCTs of ML/AI Models

Example: INSPIRE trial for improving antibiotic prescriptions using model-driven best-practice alerts.

Figure 1. Hospital Recruitment and Randomization in the INSPIRE Urinary Tract Infection Trial



MEDITECH is a hospital electronic health record system. CPOE indicates computerized provider order entry and INSPIRE, Intelligent Stewardship Prompts to Improve Real-time Empiric antibiotic selection.

^aAll analyses are as-randomized because all hospitals remained in the trial until end of intervention (no hospital withdrawals after enrollment). There was a median (IQR) of 2364 (1277-2963) patients per hospital in the CPOE bundle group and 2008 (1365-3064) in the routine stewardship group.

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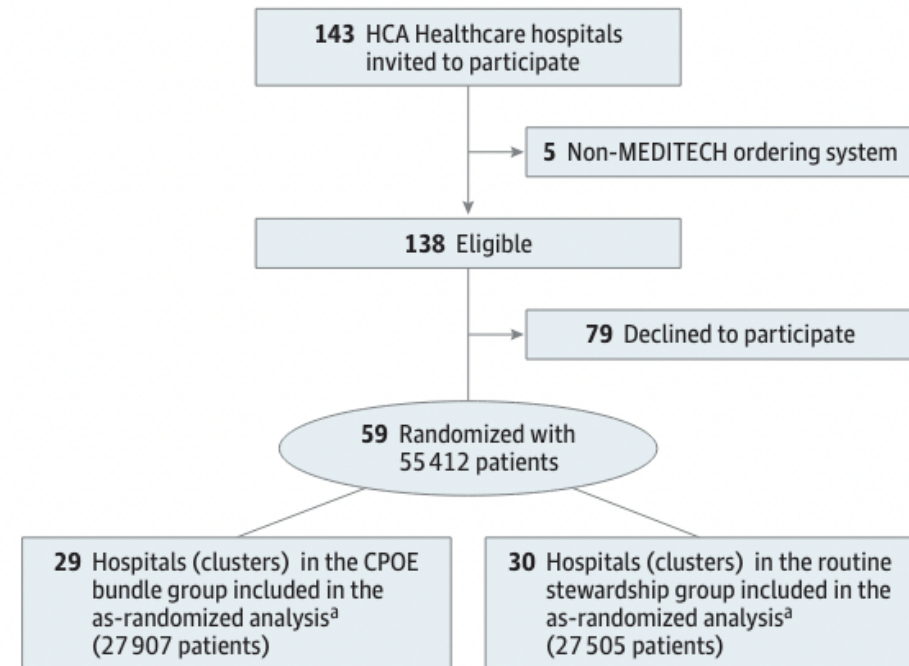
Example: INSPIRE trial for improving antibiotic prescriptions using model-driven best-practice alerts.

Important Features

- **Cluster RCT:** Randomizes hospitals to ML model vs. control.
- **Outcomes:** Compares clinical outcomes between treatment/control groups to assess the impact of model deployment.

S. K. Gohil et al. Stewardship prompts to improve antibiotic selection for urinary tract infection. JAMA, 331:2018, 6 2024a. doi: 10.1001/jama.2024.6259. URL: <http://dx.doi.org/10.1001/jama.2024.6259>.

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